Algebraic Related Structures and the Reason Behind Some Classical Constructions in Convex Geometry and Analysis

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In honor of my friend, colleague and coauthor, the great mathematician Jean Bourgain

Princeton, May 2016









What should we call "duality"?

Consider the class $Cvx(\mathbb{R}^n)$ of all *lower-semi-continuous* convex functions $f: \mathbb{R}^n \to \mathbb{R} \cup \{+\infty\}$. The Legendre transform is the map

$$\mathcal{L}\varphi(x) = \sup_{y \in \mathbb{R}^n} \left[\langle x, y \rangle - \varphi(y) \right] := \varphi^*(x)$$

(there are many "Legendre transforms": We may select 0 of the space, a scalar product and a shift for a function).

Theorem (Artstein–Milman)

1. Assume $T : Cvx(\mathbb{R}^n) \to Cvx(\mathbb{R}^n)$ satisfies:

(a)
$$T \cdot T \varphi = \varphi$$
 (for any $\varphi \in Cvx(\mathbb{R}^n)$);

(b)
$$\varphi \leq \psi$$
 implies $T\varphi \geq T\psi$.

Then T is a Legendre transform.

Note, elementary properties (a) and (b) essentially uniquely define the Legendre transform – originally a construction. (Side remark: It means that $Cvx(\mathbb{R}^n)$ has a unique duality structure.)

To be precise, we explain "essential uniqueness": Fix $\langle x, y \rangle$; $\exists c_0 \in \mathbb{R}, v_0 \in \mathbb{R}^n$, symmetric linear $B \in GL_n$ s.t.

$$(T\varphi)(x) = (\mathcal{L}\varphi)(Bx + v_0) + \langle x, v_0 \rangle + c_0.$$

How far can this point of view be extended?

Consider the fundamental constructions of Convex Geometry:

- \mathcal{K}^n is the class of closed convex sets [:=bodies] in \mathbb{R}^n .
- ▶ $\mathcal{K}_0^n := \mathcal{K}_0^n(\mathbb{R}^n) = \{K \in \mathcal{K}^n \text{ such that } 0 \in K\}$ and fixed scalar product $\langle \cdot, \cdot \rangle$. Polarity $K \in \mathcal{K}_0^n \to K^\circ$:

$$\mathcal{K}^{\circ} = \left\{ x \in \mathbb{R}^{n} \mid \langle x, y \rangle \leq 1 \; \forall y \in \mathcal{K} \right\} \in \mathcal{K}_{0}\left(\mathbb{R}^{n}\right).$$

Supporting function $K \in \mathcal{K}^n \to h_K(x)$

$$h_{\mathcal{K}}(x) = \sup_{y \in \mathcal{K}} (x, y) \in \mathcal{H}_0(\mathbb{R}^n).$$

For $K \in \mathcal{K}_0(\mathbb{R}^n)$ the gauge function M (or Minkowski functional) is the 1-homogeneous convex function $||x||_K$, "generalized" norm, s.t.

$$\mathcal{K} = \left\{ x \in \mathbb{R}^n : \; \left\| x \right\|_{\mathcal{K}} \leq 1
ight\}$$
 ,

i.e. $M(1_{K}^{\infty}) = ||x||_{K}$.

▶ Denote $\mathcal{H}_0 = \{ \|x\|_{\mathcal{K}} : \ \mathcal{K} \in \mathcal{K}_0 (\mathbb{R}^n) \}$

Polarity map

(i) The map $K \mapsto K^{\circ}$ is (essentially) a unique map $\varphi : \mathcal{K}_0 \to \mathcal{K}_0$ which

1. involution

2. reverse the order of embedding:

$$A \subset B \Rightarrow \varphi(A) \supset \varphi(B).$$

(Artstein-Milman for this class following earlier result by Böröczky-Schneider for a different but similar class.)

(This is an "analytic" characterization.)

(ii) Also a map $\psi : \mathcal{K}_0 \to \mathcal{H}_0$ (1-1 and onto) which preserves the order (i.e. $A \subset B \Rightarrow \psi_A(x) \leq \psi_B(x)$) is (essentially, up to selecting a scalar product) the above supporting map $S(\mathbf{1}_K^\infty) \equiv S(\mathcal{K}) := h_{\mathcal{K}}(x).$

(iii) The gauge map is (essentially) the unique order reversing map $M(\mathbb{1}_{K}^{\infty}) = ||x||_{K}$.

Another characterization

Now we give an "algebraic" characterization of Polarity.

K and L are in incidence relation iff $K \not\subseteq L$ and $L \not\subseteq K$.

Theorem (Artstein-Milman)

Let $T : \mathcal{K}_0(\mathbb{R}^n) \to \mathcal{K}_0(\mathbb{R}^n)$ be a bijection which preserves incidence relation (in both directions). Then $\exists B \in GL_n$ such that T is either

$$TK = BK$$

or

$$TK = (BK)^{\circ}$$

To see the usefulness of these characterizations, let us extend these very geometric constructions to the setting of functions, where geometric interpretation of these constructions is impossible.

Let us embed $\mathcal{K}(\mathbb{R}^n) = \{ \mathcal{K} \subseteq \mathbb{R}^n \mid \text{closed convex} \}$ into $Cvx(\mathbb{R}^n)$ by "convex characteristic" functions:

$$K \longrightarrow \mathbf{1}_{K}^{\infty} = \begin{cases} 0 & x \in K, \\ +\infty & x \notin K. \end{cases}$$

▶ $Cvx_0(\mathbb{R}^n) = \{f \in Cvx(\mathbb{R}^n) \text{ such that } f \ge 0 \text{ and } f(0) = 0\}$ (geometric convex functions)

Obviously, after such an embedding and using inequalities for functions, $M : \mathcal{K}_0(\mathbb{R}^n) \to \mathcal{H}_0$ is an order preserving map (1-1 and onto) and $S : \mathcal{K}_0(\mathbb{R}^n) \to \mathcal{H}_0$ is an order reversing map.

The following theorem extends the notion of Support function to the $Cvx(\mathbb{R}^n)$ and Polarity to the $Cvx_0(\mathbb{R}^n)$ setting:

Theorem (Artstein–Milman)

- 1. There is a unique order reversing extension of the support map S to $Cvx(\mathbb{R}^n)$ which is the Legendre transform.
- 2. There is a **unique** order reversing extension of the polarity map $\{\mathbf{1}_{K}^{\infty} \rightarrow \mathbf{1}_{K^{\circ}}^{\infty} \mid K \in \mathcal{K}_{0}\}$ to $Cvx_{0}(\mathbb{R}^{n}) \setminus 0$ defined by

$$\mathcal{A}f = \sup rac{\langle x, y
angle - 1}{f(y)} := f^{\circ}(x),$$

and $\mathcal{A}(0):=\mathbf{1}^\infty_{\{0\}}.$ (By extension we mean that $\mathcal{A}\mathbf{1}^\infty_K=\mathbf{1}^\infty_{K^\circ}.)$

[This type of map was used by M. in 1969 and also introduced by Rockafellar in 1970.]

Continuation of Theorem

3. Consider the order preserving map (involution)

$$\mathcal{J} = \mathcal{L}\mathcal{A} = \mathcal{A}\mathcal{L}$$

which connects two dualities (supporting map – Legendre transform \mathcal{L} , and geometric duality \mathcal{A}) and acts ray-wise (i.e. $(\mathcal{J}f)|_r = \mathcal{J}(f|_r)$ for any ray r). $\mathcal{J}: Cvx_0 \to Cvx_0$ is order preserving and it is the gauge map: \mathcal{J} is the <u>only</u> order preserving extension of the Minkowski map M onto $Cvx_0(\mathbb{R}^n)$, i.e.

$$\mathcal{J}(\mathbf{1}_{K}^{\infty}) \equiv M(\mathbf{1}_{K}^{\infty}) = \|x\|_{K}.$$

So, on the class of convex functions we have the notion of support function (\mathcal{L} transform), Minkowski functional (\mathcal{J} -map) and polarity (\mathcal{A} -transform)!

By the way, note that there are ONLY two dualities on $Cvx_0(\mathbb{R}^n)$ — \mathcal{L} and \mathcal{A} :

Theorem (Artstein–Milman)

Let $n \geq 2$. The maps \mathcal{L} and \mathcal{A} are (essentially) the only order reversing involutions on $Cvx_0(\mathbb{R}^n)$. Precisely: if $T : Cvx_0 \to Cvx_0$ is

1. involution $T \cdot T = Id$.

2. order reversing: $\forall f, g \in Cvx_0$ we have $f \leq g \Rightarrow Tf \geq Tg$, then $\exists C > 0$ and $B \in GL_n$, symmetric, s.t. either

$$\forall f \in Cvx_0, \quad Tf = \mathcal{L}(f(Bx))$$

or $\forall f \in Cvx_0, \quad Tf = C\mathcal{A}(f(Bx)).$

(When n = 1 there are 8 such different dualities)

So, on the class of geometric convex functions there are exactly two dualities: one representing the support map and another geometric notion of polarity.

Let us deviate for a few minutes from the main goal of this talk to compare these two dualities ${\cal L}$ and ${\cal A}$

- Some properties of A and L dualities:
 1. AL = LA := J (A, L and J are involutions)
 - 2. $\mathcal{A}\mathbf{1}_{K}^{\infty} = \mathbf{1}_{K^{\circ}}^{\infty}$, $\mathcal{L}\mathbf{1}_{K}^{\infty} = \|x\|_{K^{\circ}}$.

Properties of $\mathcal L$ and $\mathcal A$

For any generalized norm $\|\cdot\|$,

- 3. $(\mathcal{A}||x||)(y) = ||y||^*$; $(\mathcal{L}||x||)(y) = \mathbf{1}_{K^\circ}^{\infty}$ where K° is the unit ball of $||y||^*$.
- 4. For p > 1, $\mathcal{A}(||x||^p) = \frac{1}{p \cdot q^{p-1}} \cdot (||x||^*)^p$, where $\frac{1}{p} + \frac{1}{q} = 1$, $\mathcal{L}(||x||^p) = \frac{1}{q \cdot p^{q/p}} (||x||^*)^q$ (for p = 2, the action of \mathcal{A} coincides with the action of \mathcal{L}).
- 5. For a convex function f(t) on $\mathbb{R}^+, f(0)=0$, and any norm $\|\cdot\|,$

$$\begin{aligned} \mathcal{A}(f(\|\cdot\|)) &= (\mathcal{A}f)(\|\cdot\|^*),\\ \mathcal{L}(f(\|\cdot\|)) &= (\mathcal{L}f)(\|\cdot\|^*). \end{aligned}$$

Geometric interpretation of \mathcal{A} -duality, I

epi $(\mathcal{A}f)$ is the reflection of $(epi f)^{\circ}$:



More algebraic properties for \mathcal{L} v/s \mathcal{A}

Recall the inf-convolution operation

$$(f\Box g)(x) = \inf_{y+z=x} (f(y) + g(z)).$$

Note

$$epi(f \Box g) = epif + epig$$

and

$$\mathcal{L}(f\Box g)=\mathcal{L}f+\mathcal{L}g.$$

Similarly, using $\mathcal A\text{-transform},$ we may introduce another summation \boxdot by

$$\mathcal{A}(f \boxdot g) = \mathcal{A}f + \mathcal{A}g.$$

Geometric interpretation of the Legendre transform

Let e be the unit vector in \mathbb{R}^+ . Then

$$\operatorname{epi}(\mathcal{L}f) = \left(((\operatorname{epi} f)^\circ + e)^\circ - e \right)^\circ + e$$

or also

$$\operatorname{epi}(\mathcal{L}f) = \left(((\operatorname{epi} f - e)^{\circ} + e)^{\circ} - e \right)^{\circ}.$$



Let me add that also the notion of mixed volumes (Minkowski) and the Minkowski Polarization theorem for the family of Convex sets may be extended for the class of log-concave functions (and also for larger classes of functions).

One should introduce an analog of Minkowski summation for this class (done with L. Rotem) which leads to the notion of mixed integrals. And many deep geometric inequalities (such as Brunn–Minkowski, isoperimetric, Urysohn, Alexandrov, Alexandrov–Fenchel) may be extended to this and other classes.

Analysis.

(And again, some fundamental and non-trivial constructions are consequences of some very elementary, basic properties.)

Introduction

Let the classical **Fourier transform** \mathbb{F} on \mathbb{R}^n be

$$\mathbb{F}f=\int e^{-2\pi i\langle x,y\rangle}f(y)dy.$$

Let S be the Schwartz class of "rapidly" decreasing (infinitely smooth) functions on \mathbb{R}^n .

Theorem (Artstein, Faifman, Milman)

Assume we are given a bijective transform $\mathcal{F} : S \to S$, s.t. $\forall f, g \in S$ we have $\mathcal{F}(f \cdot g) = \mathcal{F}f * \mathcal{F}g.$

Then \exists diffeomorphism $\omega : \mathbb{R}^n \to \mathbb{R}^n \text{ s.t. either } \forall f \in S$, $\mathcal{F}f = \mathbb{F}(f \circ \omega) \text{ or } \forall f \in S$, $\mathcal{F}f = \overline{\mathbb{F}(f \circ \omega)}$. Real linearity and continuity of \mathcal{F} is the automatic consequence. Previous versions contained more conditions and were proved jointly with S. Alesker. Joining these results with the previous theorem we may state that if $\mathcal{F}: S \to S$ s.t. $\forall f, g \in S$,

$$\mathcal{F}(f \cdot g) = \mathcal{F}f * \mathcal{F}g,$$
$$\mathcal{F}(f * g) = \mathcal{F}f \cdot \mathcal{F}g,$$

then \exists linear $A \in GL_n$, $|\det(A)| = 1$, s.t. either

$$\forall f \in S, \quad \mathcal{F}f = \mathbb{F}(f \circ A)$$

or

$$\forall f \in S, \quad \mathcal{F}f = \overline{\mathbb{F}(f \circ A)}.$$

There was one "weak" point in all the previous results on recovering some constructions in an essentially unique way by very elementary properties.

Actually, this was the study of identity, the rigidity of identity.

Indeed, because the Fourier transform \mathcal{F} is already known to us, we just apply it to *a priori* unknown transform T (which has the property $T(f \cdot g) = Tf * Tg$) and then

$$(\mathcal{F}T)(f \cdot g) = (\mathcal{F}Tf) \cdot (\mathcal{F}Tg).$$

So we need to show that the map preserving product is, essentially, *identity*!!

We want a different example. And here a new series of results of purely analytic nature starts.

The chain rule operator equation and derivation construction

Chain rule for $f, g \in C^1(\mathbb{R}) : D(f \circ g) = (Df) \circ g \cdot Dg$. Let $T : C^1(\mathbb{R}) \to C(\mathbb{R})$ be an operator satisfying the functional equation

 $T(f \circ g)(x) = (Tf)(g(x)) \cdot (Tg)(x); \quad f, g \in C^{1}(\mathbb{R}), x \in \mathbb{R}.$ (1)
Which operators T satisfy (1)?

Examples:

a)
$$p > 0$$
, $(Tf)(x) = |f'(x)|^p$ and
 $(Tf)(x) = \operatorname{sgn} f'(x) |f'(x)|^p$ both satisfy (1).
b) Let $H \in C(\mathbb{R})$, $H > 0$. Define $(Tf)(x) = H(f(x))/H(x)$
Then T satisfies (1).
c) Consider $T : C^1(\mathbb{R}) \to C(\mathbb{R})$, $(Tf)(x) =$
 $\begin{cases} f'(x) & f \in C^1(\mathbb{R}) \text{ bijective} \\ 0 & 0 \end{cases}$. Then T satisfies (1).

else

Solutions of the chain rule operator equation

Multiplying two solutions of the chain rule yields again a solution. $T: C^k(\mathbb{R}) \to C(\mathbb{R})$ is C^k -non-degenerate if $T|_{C_b^k(\mathbb{R})} \neq 0$ where $C_b^k(\mathbb{R})$ are the (half-) bounded functions in $C^k(\mathbb{R})$. Here $k \in \mathbb{N}_0$. Theorem [Artstein-König-Milman]

Assume $T: C^k(\mathbb{R}) \to C(\mathbb{R})$ satisfies the chain rule

$$T(f \circ g) = (Tf) \circ g \cdot Tg; \quad f, g \in C^{k}(\mathbb{R})$$

for $k \in \mathbb{N}_0$ and that T is C^k -non-degenerate. Then there is $p \ge 0$ and $H \in C_{>0}(\mathbb{R})$ such that for any $f \in C^k(\mathbb{R})$

$$(Tf)(x) = \frac{H(f(x))}{H(x)} |f'(x)|^{p} \{ \text{sgn } f'(x) \},$$

and this also holds for $k = \infty$, i.e. $f \in C^{\infty}(\mathbb{R})$.

Remarks

1. By this formula T automatically extends to $C^1(\mathbb{R})$. So the natural Dom T is C^1 .

2. Let us add the following normalization condition:

$$T(-2\cdot \mathrm{Id})=-2$$
.

Then the unique solution of the chain rule operator equation is the derivative T(f) = f'.

(Now we don't see it as a study of the identity map.)

3. The result is also valued for operators acting on the family of polynomes $P(\mathbb{R}^n)$, however, ONLY if we add some (although weak) pointwise continuity assumption (actually, at one point 0). Under such assumptions the statement is true also for the class of entire functions. Note, we don't have **any** continuity assumptions in the theorem.

However, on so small a family as Polynomials, the statement without such an assumption is not true (example: $T(P) = \deg P$, and many others. An interesting question is to describe all $T: P \rightarrow P$ s.t. $T(P \circ Q) = TP \cdot TQ$).

The chain rule is a very natural (and very elementary) way to define a non-trivial construction – derivation.

Steps in the Proof

- a) Show "localization": There is $F : \mathbb{R}^{k+2} \to \mathbb{R}$ such that $Tf(x) = F(x, f(x), ..., f^{(k)}(x))$ for all $f \in C^k(\mathbb{R})$ and $x \in \mathbb{R}$.
- b) Analyze the structure of the representing function F: $F(x, \alpha_0, ..., \alpha_k) = \frac{H(\alpha_0)}{H(x)}K(\alpha_1)$, K multiplicative, F independent of $\alpha_2, ..., \alpha_k$ if $k \ge 2$.
- c) Show the measurability and then the continuity of the coefficient functions occurring in *F*.

Stability of the Chain Rule

 $T: C^1(\mathbb{R}) \to C(\mathbb{R})$ is locally non-degenerate if \forall open interval $J \subset \mathbb{R}, \forall x \in J, \exists g \in C^1(\mathbb{R}), y \in \mathbb{R}, \text{ s.t. } g(y) = x, \operatorname{Im}(g) \subset J$ and $Tg(y) \neq 0$.

Theorem (König-Milman)

Fix $T: C^1(\mathbb{R}) \to C(\mathbb{R})$ and $B: \mathbb{R}^3 \to \mathbb{R}$ such that $\forall f, g \in C^1$ and $\forall x \in \mathbb{R}$

 $T(f \circ g)(x) = Tf \circ g(x) \cdot Tg(x) + B(x, f \circ g(x), g(x)).$

Assume that T is locally non-degenerate and Tf depends non-trivially on f'.

Then B = 0 (and T satisfies the chain rule).

Even more rigidity

Consider the "chain rule inequality"

$$T(f \circ g) \leq (Tf) \circ g \cdot Tg$$
 (*)

for $T : C^1(\mathbb{R}) \to C(\mathbb{R})$, $\mathsf{Dom}(T) = C^1(\mathbb{R})$.

Assume that T satisfies the following:

- ▶ non-degeneration: \forall open interval $I \subset \mathbb{R}$, $\forall x \in I$, $\exists g \in C^1(\mathbb{R})$ s.t. g(x) = x, $\operatorname{Im}(g) \subset I$ and Tg(x) > 1.
- ▶ *T* is pointwise continuous: $\forall f, f_n \in C^1(\mathbb{R})$ s.t $f_n \to f$, $f'_n \to f'$ uniformly on compact subsets we have $(Tf_n)(x) \to (Tf)(x)$ pointwise for all $x \in \mathbb{R}$.

Theorem (König-Milman)

For T as above assume also $\exists x \in \mathbb{R} \text{ s.t } T(-Id)(x) < 0$. Then $\exists H \in C(\mathbb{R}), H > 0, \exists p > 0 \text{ and } A \ge 1 \text{ s.t}$

$$Tf = \begin{cases} \frac{H \circ f}{H} |f'|^p & \text{for } f' \ge 0\\ -A \frac{H \circ f}{H} |f'|^p & \text{for } f' < 0. \end{cases}$$

Note:

- ► For A = 1, T satisfies the chain rule equation: we have equality in (*).
- ► For both f and g non-decreasing we automatically have equality in (*).
- Actually, the same is true if for some C > 0

$$T(f \circ g) \leq C \cdot (Tf) \circ g \cdot Tg$$

and even much more generally (the answer is slightly modified).

Theorem (König-Milman)

Assume that $T : C^1(\mathbb{R}) \to C(\mathbb{R})$ is pointwise continuous and non-degenerate. Suppose further that there is a function $S : \mathbb{R}^3 \to \mathbb{R}$ such that the perturbed chain operator inequality

 $|T(f \circ g)(x) - (Tf)(g(x)) \cdot (Tg)(x)| \le S(x, (f \circ g)(x), g(x))$

holds for all $f, g \in C^1(\mathbb{R})$ and all $x \in \mathbb{R}$. Then there are p > 0and a positive continuous function $H : \mathbb{R} \to \mathbb{R}_{>0}$ such that for all $f \in C^1(\mathbb{R})$ and all $x \in \mathbb{R}$

$$Tf(x) = \frac{H(f(x))}{H(x)} sgn \ f'(x)|f'(x)|^p.$$

This implies that we may choose S = 0, i.e. that we have equality

$$T(f \circ g)(x) = (Tf)(g(x)) \cdot (Tg)(x), \qquad f, g \in C^1(\mathbb{R}), x \in \mathbb{R}.$$

The following classically sound functional statement is used: We say that $K : \mathbb{R} \to \mathbb{R}$ is submultiplicative if

$$K(\alpha\beta) \leq K(\alpha)K(\beta)$$
, $\forall \alpha, \beta \in \mathbb{R}$.

Theorem (König-Milman)

Let K be submultiplicative, measurable and continuous at 0 and at 1. Assume K(-1) < 0 < K(1). Then $\exists p > 0$ s.t.

$$K(\alpha) = \begin{cases} \alpha^{p} & \text{for } \alpha \geq 0\\ -A \left| \alpha \right|^{p} & \text{for } \alpha < 0 \end{cases}$$

(and $K(-1) = -A \leq -1$).

[every assumption in the theorem is needed]

As a corollary, K must be multiplicative on \mathbb{R}^+ .

Second order chain rule formulas

(We will see a new phenomenon here)

For $f, g \in C^2(\mathbb{R})$ one has $D^2(f \circ g) = D^2 f \circ g \cdot g'^2 + f' \circ g \cdot D^2 g.$ (*)

We study the solutions of a generalized operator functional equation:

Let $k \ge 2$ and $T: C^k(\mathbb{R}) \to C(\mathbb{R})$, $A_1, A_2: C^{k-1}(\mathbb{R}) \to C(\mathbb{R})$ be such that

 $T(f \circ g) = Tf \circ g \cdot A_1g + A_2f \circ g \cdot Tg; \quad f, g \in C^k(\mathbb{R}).$ (2)

A is *isotropic* if it commutes with all shift operators.

(T, A) is C^k -non-degenerate if for all open sets $J \subset \mathbb{R}$ and $x \in J$ there are $y_1, y_2 \in \mathbb{R}$ and $g_1, g_2 \in C^k(\mathbb{R})$ such that $Im(g_i) \subset J$, $g_1(y_1) = x = g_2(y_2)$ and $z_i = (Tg_i(y_i), Ag_i(y_i)) \in \mathbb{R}^2$ are linearly independent for i = 1, 2.

Note: For $A_1 = A_2 = \frac{1}{2}T$, (2) is just the chain rule operator equation (1). Non-degeneration excludes this.

There are very few operators A_1 ; A_2 which lead to (2) with non-trivial solutions. Let us list all of them by Dom T:

That is all. No other combination of A_1 and A_2 may lead to any (non-trivial) solutions. We know the formulas for solutions in any of these cases. Of course, solutions in the cases (0) Dom T = C and (1) Dom T = C' are also solutions in the remaining cases. Let me describe the additional solutions for the cases (2) and (3).

Case Dom $T = C^2$. $\exists p \ge 1$, $c(x) \not\equiv 0$ and $H(x) \in C(\mathbb{R})$ s.t.

 $Tf = \left(cf'' + [H \circ f \cdot f' - H] \cdot f'\right) \cdot |f'|^{p-1} \{\operatorname{sgn} f'\}$

(So, for H = 0; p = 1, the answer is Tf = cf''.)

To describe the case Dom $T = C^3$, we need to introduce the Schwarzian derivative S of a $C^3(\mathbb{R})$ -function f:

$$Sf = \left(\frac{f''}{f'}\right)' - \frac{1}{2}\left(\frac{f''}{f'}\right)^2 = \frac{f'''}{f'} - \frac{3}{2}\left(\frac{f''}{f'}\right)^2$$

Note $f'^2 S f = f''' f' - \frac{3}{2} f''^2$ is also defined if f' = 0. S satisfies the composition rule

$$S(f \circ g) = Sf \circ g \cdot g'^2 + Sg.$$

The kernel of S consists of the fractional linear transformations $f(x) = \frac{ax+b}{cx+d}$. Hence for such f, S is invariant: $S(f \circ g) = Sg$. Although the Schwarzian derivative is mainly important in complex analysis, e.g. for conformal mappings, univalent functions and complex dynamics, we only study real versions of S. Now, for Dom $T = C^3(\mathbb{R})$ (in addition to the previous solutions) we have (for c(x) and $H(x) \subset C(\mathbb{R})$, $p \ge 2$)

$$Tf = (c \cdot Sf + H(f)f'^2 - H)|f'|^p \{\operatorname{sgn} f'\}$$

(So both f'' and f''' are coming through S.)

Note that there is no solution of (2) depending on the fourth or higher derivative of f (!)

So the natural domains of solutions of (2) are $C^k(\mathbb{R})$ for $k \in \{0, 1, 2, 3\}$.

Two initial conditions may determine the form of T, e.g.

$$T(x^{2}) = 2, T(x^{3}) = 6x \text{ yields}$$

$$Tf = f'', \qquad A_{1}f = f'^{2}, A_{2}f = f'$$
and
$$T(x^{2}) = -6, T(x^{3}) = -36x^{2} \text{ implies the solution}$$

$$Tf = f'^{2}Sf, \qquad A_{1}f = f'^{4}, A_{2}f = f'^{2}$$
(4) The solutions for A - A dense d only on f'. Therefore the

(4) The solutions for A_1 , A_2 depend only on f'. Therefore the natural domain for A_1 and A_2 is $C^1(\mathbb{R})$.

Extra information

The solutions in the case C^1

1a.
$$(Tg)(x) = (c \ln |g'(x)| + H(g(x)) - H(x))|g'(x)|^{p} \{ \operatorname{sgn} g'(x) \};$$

1b.
$$(Tg)(x) = H(g(x))|g'(x)|^q [\operatorname{sgn} g'(x)] - H(x)|g'(x)|^p \{\operatorname{sgn} g'(x)\};$$

1c. $(Tg)(x) = c|g'(x)|^p \sin(d \ln |g'(x)|) \{ \operatorname{sgn} g'(x) \}.$

Approach through Leibniz rule

Theorem (König-Milman)

Suppose $T: C^1(\mathbb{R}) \to C(\mathbb{R})$ satisfies the Leibniz product formula

$$T(f \cdot g) = Tf \cdot g + f \cdot Tg;$$
 $f, g \in C^1(\mathbb{R}).$

Then there are continuous functions c(x), d(x) such that

 $Tf(x) = c(x)f'(x) + d(x)f(x)\ln|f(x)|, \qquad f \in C^1(\mathbb{R}), x \in \mathbb{R}.$

(If T also maps $C^2(\mathbb{R})$ into $C^1(\mathbb{R})$, then Tf = cf'.)

We see that there exist (only!) two domains on which Leibniz's rule acts:

- 1. $C(\mathbb{R})$ with the only solution being the entropy function (Goldmann-Šemrl);
- 2. $C^1(\mathbb{R})$ with 2 solutions, f' and $f \cdot \ln |f|$, and their linear combination.

Theorem (König-Milman)

Let V, T_1 , T_2 : $C^1(\mathbb{R}) \to C(\mathbb{R})$ be operators such that

$$V(f \cdot g) = (T_1 f) \cdot g + f \cdot (T_2 g)$$
(3)

is satisfied for all $f, g \in C^1(\mathbb{R})$. Then there are continuous functions $a, b, c_1, c_2 \in C(\mathbb{R})$ such that with

$$(Tf)(x) := b(x)f'(x) + a(x)f(x)\ln|f(x)|$$

we have

$$(Vf)(x) = (Tf)(x) + (c_1(x) + c_2(x))f(x)$$

$$(T_1f)(x) = (Tf)(x) + c_1(x)f(x)$$

$$(T_2f)(x) = (Tf)(x) + c_2(x)f(x).$$

The formula for (Tf)(x) represents the general solution of (4) in the case when $V = T_1 = T_2 = T$.

It is again surprising how rigid are simple relations which define (almost uniquely) basic operations/constructions in geometry and analysis. One more example:

Theorem (König-Milman)

Let $k \in \mathbb{N}$, $T : C^k(\mathbb{R}) \to C(\mathbb{R})$ be an operator and $B : \mathbb{R} \times \mathbb{R}^k \times \mathbb{R}^k \to \mathbb{R}$ be a function such that

$$T(f \cdot g)(x) = Tf(x) \cdot g(x) + f(x) \cdot Tg(x) +$$
$$B(x, f(x), \dots, f^{(k-1)}(x), g(x), \dots g^{(k-1)}(x))$$

holds for all $f, g \in C^{k}(\mathbb{R})$ and $x \in \mathbb{R}$. Let T annihilate all polynomials of order $\leq k - 1$. Then $Tf = d \cdot f^{(k)}$ for $d \in C(\mathbb{R})$, and B has the form

$$B(x, f(x), \dots, g^{(k-1)}(x)) = d(x) \sum_{j=1}^{k-1} \binom{k}{j} f^{(j)}(x) g^{(k-j)}(x).$$

And the Laplacian case

Theorem (König-Milman)

Let $n \in \mathbb{N}$. Let $T : C^2(\mathbb{R}^n, \mathbb{R}) \to C(\mathbb{R}^n, \mathbb{R})$ be an operator and B be a function $B : \mathbb{R}^n \times \mathbb{R} \times \mathbb{R}^n \times \mathbb{R} \times \mathbb{R}^n \to \mathbb{R}$ s.t.

$$T(f \cdot g)(x) = Tf(x)g(x) + f(x)Tg(x) + B(x, f(x), f'(x), g(x), g'(x))$$

holds for all $f, g \in C^2(\mathbb{R}^n, \mathbb{R})$ and all $x \in \mathbb{R}^n$. Let T annihilate all affine functions and be orthogonally invariant, i.e. $T(f \circ \varphi) = (Tf) \circ \varphi$ for all $\varphi \in O(n)$. Then T is a multiple of the Laplacian: there is $d \in C(\mathbb{R}_{\geq 0}, \mathbb{R})$ such that

$$Tf(x) = d(||x||)\Delta f(x),$$

 $B(x, f(x), f'(x), g(x), g'(x)) = d(||x||) \langle f'(x), g'(x) \rangle.$

holds for all $f, g \in C^2(\mathbb{R}^n, \mathbb{R}), x \in \mathbb{R}^n$, and ||x|| is Euclidean norm.