- My name is **Shay Moran**
- Before coming to IAS, I spent a year in California
  - at UCSD hosted by Shachar Lovett
  - at the **Simons Institute in Berkeley**
- I did my Ph.D. at the **Technion**, supervised by **Amir Yehudayoff** and **Amir Shpilka**.
- Research interests: math ∩ computer-science
  - machine learning and its links with other fields
- Today I will present a problem in *abstract convexity*

# Weak epsilon nets versus the Radon number

based on joint work with Amir Yehudayoff (Technion)

## Weak epsilon nets for convex sets

**Theorem.** [Bárány-Füredi-Lovász '90, Alon-Bárány-Füredi-Kleitman '92, Chazelle-Edelsbrunner-Grigni-Guibas-Sharir-Welzl '93]

For every distribution  $\mu$  on  $\mathbb{R}^d$  and  $\epsilon > 0$  there is a set N s.t:

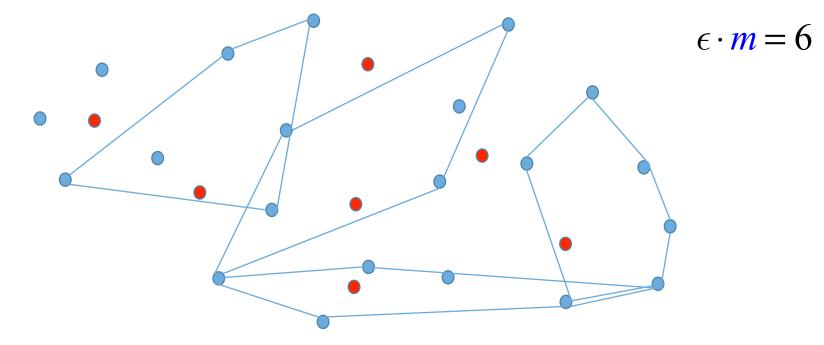
1.  $N \cap C \neq \emptyset$  for every <u>convex</u> *C* with  $\mu(C) \ge \epsilon$ .

2.  $|N| \lesssim (1/\epsilon)^d$ .

- N is called a weak  $\epsilon$ -net w.r.t  $\mu$
- bound *does not depend* on μ!
- used in Alon & Kleitman's proof of the (*p,q*)-conjeture by Hadwiger & Debrunner
- some conjecture the right bound is some  $\tilde{O}(d \, / \, \epsilon)$

### An example in the plane

Given:  $\mu$  is the uniform distribution on m points,  $\epsilon > 0$ 



#### Objective: find a small $\epsilon$ -net w.r.t $\mu$ .

(hit every convex set with at least 6 blue points)

What properties of convex sets enable weak epsilon nets?

- Proofs use a lot of geometry
- Goal: identify a simple/basic property of convex sets that captures existence of weak epsilon nets
- notion of dimension?
- It is convenient to consider the framework of *abstract convexity* [Levi '51, Danzer-Grünbaum-Klee '63, Kay-Womble '71]

### Abstract convexity spaces

**Definition.** A <u>convexity space</u> is a pair (X,F) where F is a family of subsets of X that is closed under intersections.

#### Some convexity spaces:

- closed/compact sets
- subgroups/subfields/subrings
- euclidean convex sets, grid convex sets
- geodesic convex sets

["Math is the art of giving the same name to different things" – Henri Poincaré]

**Definition.** (*X*,*F*) has <u>weak  $\epsilon$ -nets</u> if there is  $n=n(\epsilon)$  s.t: for every distribution  $\mu$  there are n points that hit all sets in *F* with measure at least  $\epsilon$ .

## The Radon number of abstract convexity spaces

**Theorem.** [Radon '21] Any d+2 points in  $\mathbb{R}^d$  can be partitioned into two sets whose convex hulls intersect.



**Definition.** The <u>Radon number</u> of (X,F) is the smallest integer r s.t any set of r points can be partitioned into two sets whose <u>convex hulls</u> intersect.

## Conjecture: *Radon number* captures weak epsilon nets

#### **Conjecture.**

Let (X,F) be a convexity space. The following are equivalent

- 1. (X,F) has a finite radon number.
- 2. (X,F) has a weak  $\epsilon$ -nets of for every  $\epsilon > 0$ .

 $2 \rightarrow 1$  is known [M-Yehudayoff '17].

- proof by a simple reduction to the *chromatic number of* **Kneser graphs** 
  - analyzing the chromatic number of Kneser graphs [Lovász 1978] is one of the first applications of the **topological method** in combinatorics.

Theorem: *Radon number* captures weak epsilon nets for separable spaces

**Theorem.** [M-Yehudayoff '17] Let (*X*,*F*) be a <u>separable</u> convexity space. The following are equivalent 1. (*X*,*F*) has a finite radon number. 2. (*X*,*F*) has a weak  $\epsilon$ -nets of finite size for every  $\epsilon > 0$ .

**Definition.** Let (*X*,*F*) be a convexity space. A <u>hyperplane</u> is a partition of *X* into two convex sets (members of *F*).

**Definition.** (*X*,*F*) is <u>separable</u> if for every  $C \in F$  and  $x \notin C$  there is a <u>hyperplane</u> separating x and C. [abstraction of Hahn-Banach]

Remains open: does a finite Radon number imply weak epsilon nets in non-separable spaces?

**Example.** (non-separable convexity space)

Let *G* be a group with identity *e*.

Consider the convexity space (G,F), where  $F = \{H \searrow \{e\} : H \le G\}.$ 

Radon number *r* means:

any *r* elements can be partitioned to two sets A,B whose generated groups  $\langle A \rangle$ ,  $\langle B \rangle$  share an element  $x \neq e$ .

# Thank you!