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- The group operation \star of the semidirect product $\mathbb{R}^2 \rtimes_{\mathbf{A}} \mathbb{R}$, where $+$ is the group operation of \mathbb{R}^2 and \mathbb{R} , is given by

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- The intrinsically flat horizontal planes $\mathbb{R}^2 \rtimes_{\mathbf{A}} \{t\}$ in $\mathbb{R}^2 \rtimes_{\mathbf{A}} \mathbb{R}$ have constant mean curvature $\text{trace}(\mathbf{A})/2$.

Notation and language:

- Y denotes a simply connected 3-dimensional homogeneous manifold.
- $H(Y) = \text{Inf}\{\max |H_M| : M = \text{immersed closed surface in } Y\}$,
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- In particular, $H(Y) = 1$ if $Y = \mathbb{H}^3$ and $H(Y) = 1/2$ if $Y = \mathbb{H}^2 \times \mathbb{R}$.

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in the case \mathbf{Y} is diffeomorphic to \mathbf{R}^3 uses the **existence** of a $\mathbf{H}(\mathbf{Y})$ -foliation $\overline{\mathcal{F}}$ of \mathbf{Y} by doubly-periodic planes of quadratic area growth to demonstrate:

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2. In this case where \mathbf{Y} is diffeomorphic to \mathbf{R}^3 ,
 - The leaves of the foliation \mathcal{F} of \mathbf{Y} are invariant under a **1**-parameter group of isometries of \mathbf{Y} .
 - By the maximum principle, there are **no** closed immersed $\mathbf{H}(\mathbf{Y})$ -surfaces in \mathbf{Y} .

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- (2) If X is diffeomorphic to \mathbb{R}^3 , then the values $H \in \mathbb{R}$ for which there exists a sphere of constant mean curvature H in M are exactly those with $|H| > \text{Ch}(X)/2$.

Theorem (Geometry of \mathbf{H} -spheres, 2017 Meeks-Mira-Pérez-Ros)

Let \mathbf{S} be an \mathbf{H} -sphere in \mathbf{M} .

- 1 If $\mathbf{H} = 0$ and \mathbf{X} is a product $\mathbf{S}^2 \times \mathbb{R}$, where \mathbf{S}^2 is a sphere of constant curvature, then \mathbf{S} is totally geodesic, stable and has nullity $\mathbf{1}$ for its Jacobi operator.

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- 2 **Otherwise**, S has index 1 and nullity 3 for its Jacobi operator and the immersion of S into M extends as the boundary of an isometric immersion $F: B \rightarrow M$ of a Riemannian 3-ball B which is mean convex. (When X is $S^2 \times \mathbb{R}$, this follows by work of Abresch, Rosenberg and Souam.)

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- 3 There is a point $\mathbf{p}_S \in \mathbf{M}$, called the **center of symmetry** of \mathbf{S} , such that every isometry of \mathbf{M} that fixes \mathbf{p}_S also leaves invariant \mathbf{S} .

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Theorem (Daniel-Mira (2013), Meeks (2013))

- If **X** is the Lie group **Sol**₃ with the left invariant metric

$$e^{2z} dx^2 + e^{-2z} dy^2 + dz^2,$$

then **H**-spheres in **X** are unique, embedded and have index 1.

- After left translation, these spheres have ambient symmetry group generated by reflections in the (x, z) and (y, z) -planes and rotations by π around the two lines $y = \pm x$ in the (x, y) -plane.

Theorem (Classification Theorem for \mathbf{H} -spheres, Meeks-Mira-Pérez-Ros)

Suppose \mathbf{X} is a simply connected 3-dimensional homogeneous manifold different from $\mathbf{S}^2(\kappa) \times \mathbb{R}$, where $\mathbf{S}^2(\kappa)$ is a sphere of curvature κ .

- \mathbf{X} diffeomorphic to $\mathbf{S}^3 \implies$ the moduli space of \mathbf{H} -spheres in \mathbf{X} is parameterized by the mean curvature values $\mathbf{H} \in \mathbb{R}$.
- \mathbf{X} diffeomorphic to $\mathbf{R}^3 \implies$ moduli space of \mathbf{H} -spheres in \mathbf{X} is parameterized by the $\mathbf{H} \in \mathbb{R}$ values, where $|\mathbf{H}| \in (\mathbf{H}(\mathbf{X}), \infty)$.
- \mathbf{X} diffeomorphic to $\mathbf{S}^3 \implies$ the areas of all \mathbf{H} -spheres form a half-open interval $(0, \mathbf{A}(\mathbf{X})]$.
- \mathbf{H} -spheres in \mathbf{X} are **Alexandrov embedded** with **index 1**, **nullity 3**.

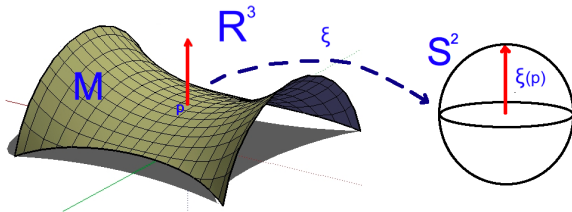
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In the following proof, choose a metric Lie group structure on \mathbf{X} .



Definition (Left invariant Gauss map)

- Let \mathbf{X} be a 3-dimensional metric Lie group.
- Given an oriented immersed surface $f: \mathbf{M} \rightarrow \mathbf{X}$ with unit normal vector field ξ , the **left invariant Gauss map** of \mathbf{M} is the map $\mathbf{G}: \mathbf{M} \rightarrow \mathbf{S}^2 \subset T_e \mathbf{X}$ that assigns to each $\mathbf{p} \in \mathbf{M}$, the unit tangent vector to \mathbf{X} at the identity element \mathbf{e} given by left translation:

$$(dl_{f(\mathbf{p})})_{\mathbf{e}}(\mathbf{G}(\mathbf{p})) = \xi_{\mathbf{p}}.$$

Steps of the proof of the Classification Theorem for \mathbf{H} -spheres.

Throughout Σ denotes a fixed \mathbf{H}_0 -sphere in \mathbf{X} of index 1.

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- Step 1: The moduli space $\mathcal{M}(\mathbf{X})$ of non-congruent index-1 \mathbf{H} -spheres in \mathbf{X} is an analytic 1-manifold locally parameterized by its mean curvature values: **Implicit Function Theorem**.

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- **Step 2:** The left invariant Gauss map $\mathbf{G}: \Sigma \rightarrow \mathbf{S}^2 \subset \mathbf{T}_e(\mathbf{X})$ is a **degree-1 diffeomorphism**: **Nodal Domain Argument + Rep Thm**.

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- **Step 4:** **Area estimates** for Σ .

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- **Conclusions:**
 - The space of non-congruent \mathbf{H} -spheres in \mathbf{X} equals $\mathcal{M}(\mathbf{X})$ which is an interval parameterized by the mean curvature values in $[0, \infty)$ if \mathbf{X} is isomorphic to $\mathbf{SU}(2)$ and otherwise, in the interval $(\mathbf{H}(\mathbf{X}), \infty)$.
 - Each \mathbf{H} -sphere in \mathbf{X} has **index 1** and **nullity 3**.
 - Each \mathbf{H} -sphere in \mathbf{X} is the boundary of an immersed **3**-ball $\mathbf{F}: \mathbf{B} \rightarrow \mathbf{X}$ on its mean convex side (Alexandrov embedded).
 - If \mathbf{X} is isomorphic to $\mathbf{SU}(2)$, then the areas of \mathbf{H} -spheres in \mathbf{X} form a half-open interval $(0, \mathbf{A}(\mathbf{X})]$. □

Theorem (Curvature Estimates for H -Disks, Meeks-Tinaglia 2018)

Fix $\varepsilon, H_0 > 0$ and a complete locally homogenous 3-manifold X . $\exists C > 0$ s.t. for all embedded $(H \geq H_0)$ -disks D in X :

$$|A_D|(p) \leq C \quad \text{for all } p \in D \text{ s.t. } \text{dist}_D(p, \partial D) \geq \varepsilon,$$

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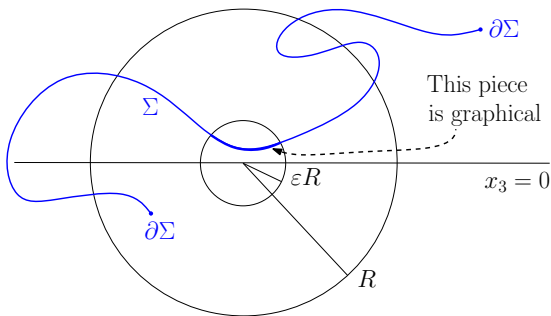
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- **Step 4:** One extends the double multigraph in the forming helicoid near $p_n \in D(n)$ a definite distance for n large, a contradiction.

Theorem (One-sided curvature estimate for \mathbf{H} -disks, Meeks-Tinaglia)

$\exists C, \varepsilon > 0$ s.t. for any embedded \mathbf{H} -disk $\Sigma \subset \mathbf{R}^3$ as in the figure below:

$$|\mathbf{A}_\Sigma| \leq \frac{C}{R} \text{ in } \Sigma \cap \mathbb{B}(\varepsilon R) \cap \{x_3 > 0\}.$$



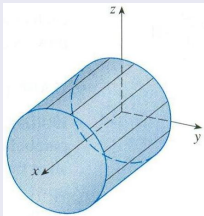
This result generalizes the one-sided curvature estimates for minimal disks by Colding-Minicozzi, and uses their work in its proof.

New uniqueness results for CMC surfaces.

Old Question

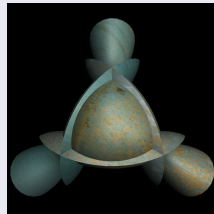
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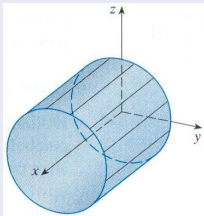
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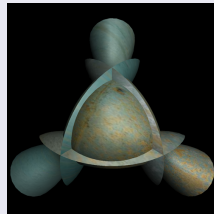
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Answer (Meeks-Tinaglia)

Yes!

Corollary (Radius Estimates for \mathbf{H} -Disks, Meeks-Tinaglia 2017)

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Corollary (Meeks-Tinaglia 2017)

A complete simply connected H -surface embedded in \mathbf{R}^3 with $H > 0$ is a round sphere.

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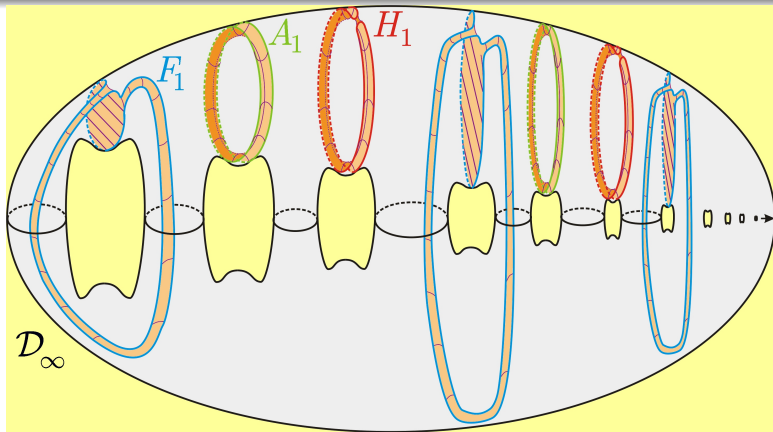
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Item 3 in the above theorem holds for 3-manifolds which have bounded absolute sectional curvature; in particular it holds in closed Riemannian 3-manifolds.

Universal domain for Embedded Calabi-Yau problem?



- $\mathcal{D}_\infty =$ above **bounded domain, smooth except at p_∞** on right.
- **Ferrer, Martin and Meeks** conjecture: An open surface **properly embeds as a complete minimal surface in \mathcal{D}_∞** \iff every end has **infinite genus** \iff it admits a complete bounded minimal embedding in \mathbb{R}^3 .

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- The General Calabi-Yau Conjecture is **true** for $\Sigma \iff \Sigma$ has a countable $\#$ of ends $\iff \Sigma$ has at most **2** limit ends.

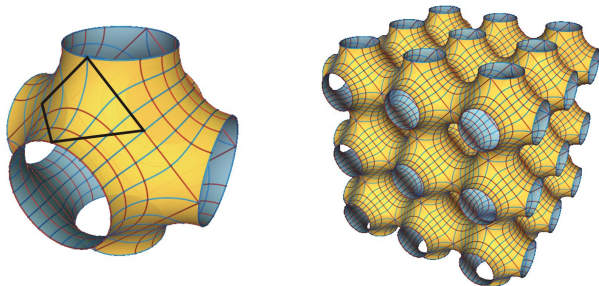


Figure: A body-centered cubic interface or Fermi surface in salt crystal.

Next theorem is motivated by the study of \mathbb{R}^3 -periodic H -surfaces that appear as interfaces in material science or as equipotential surfaces in crystals. This result contrasts with the failure of area estimates for compact minimal surfaces of genus $g > 2$ in any flat \mathbb{R}^3 -torus (Traizet).

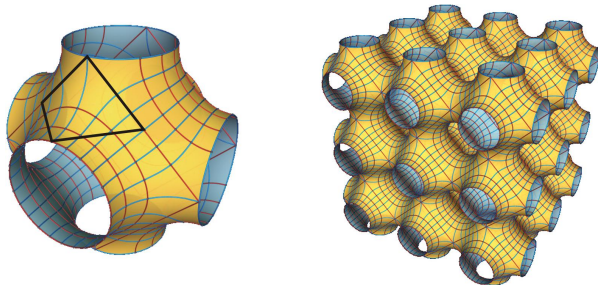


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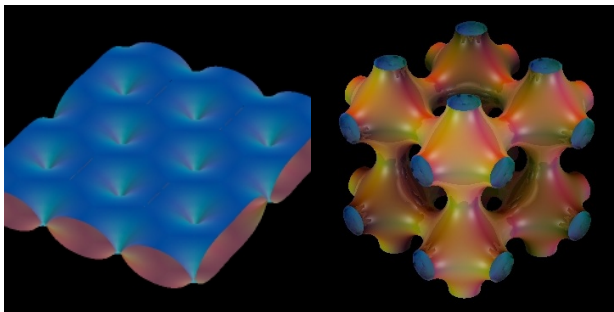
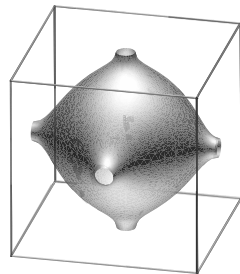
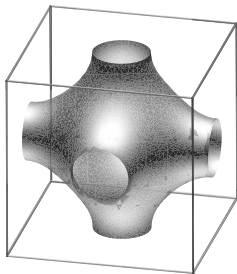
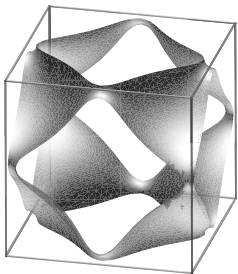
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Theorem (Meeks-Tinaglia(2016))

Given a flat 3 -torus \mathbb{T}^3 and $H > 0$, $\forall g \in \mathbb{N}$, $\exists C(g, H)$ s.t. a closed H -surface Σ embedded in \mathbb{T}^3 with genus at most g satisfies

$$\text{Area}(\Sigma) \leq C(g, H).$$

Closed H-surfaces in a flat 3-torus. By K. Grosse-Brauckmann (top) and N. Schmitt (bottom)



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- 2 For **every** closed Riemannian 3-manifold X and any non-negative integer g , the space of strongly Alexandrov embedded closed surfaces in X of genus at most g and constant mean curvature $H \in [a, b]$ is **compact**. (Similar compactness result holds for any fixed smooth compact family of metrics on X .)

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Theorem (Coskunuzer-Meeks-Tinaglia(2017))

- For every $H \in [0, 1)$, \exists a complete embedded stable H -plane that is **nonproper** in the hyperbolic 3-space \mathbb{H}^3 .
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Theorem (Meeks-Ramos(2017))

- Suppose X is a complete hyperbolic 3-manifold with finite volume, $H \in [0, 1)$ and M is a properly immersed H -surface. Then:
 - M has finite area and total curvature $2\pi\chi(M)$.
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- There does **NOT** exist a complete hyperbolic 3-manifold of finite volume containing a proper embedding of M with constant mean curvature $H \geq 1$.

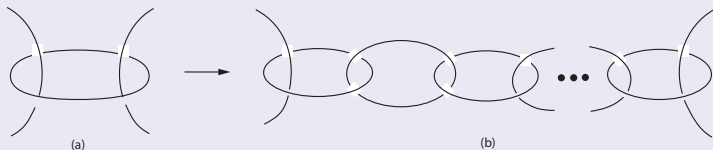


Figure: Replacing (a) with (b) preserves hyperbolicity of the complement.

Theorem (The Chain Lemma)

Let L be a link in a 3-manifold M such that the link complement $M \setminus L$ admits a complete hyperbolic metric of finite volume. Suppose that there is a sphere S in M bounding a ball B that intersects L as in Figure 2 (a). Let L' be the resulting link obtained by replacing $L \cap B$ by the components as appear in Figure 2 (b). Then $M \setminus L'$ admits a complete hyperbolic metric of finite volume.

Theorem (The Switch Move Lemma)

Let L be a link in a 3-manifold M such that $M \setminus L$ admits a complete hyperbolic metric of finite volume. Let $\alpha \subset M$ be the closure in M of a complete, properly embedded geodesic of $M \setminus L$ with distinct endpoints on L . Let B be a closed ball in M containing α in its interior and such that $B \cap L$ is composed of two arcs in L , as in Figure 3. Let L_1 be the resulting link in M obtained by replacing $L \cap B$ by the components as appearing in Figure 4 (b). Then $M \setminus L_1$ admits a complete hyperbolic metric of finite volume.

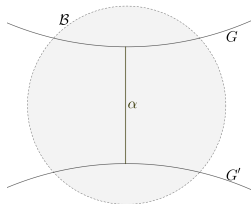
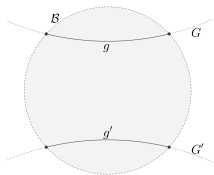
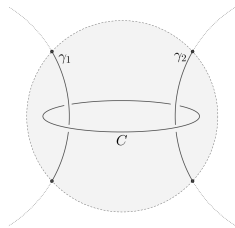


Figure: The trace of a geodesic α of $(M \setminus L, h)$ joins distinct components G, G' of L , and a neighborhood \mathcal{B} of α intersects L in two arcs $g \subset G$ and $g' \subset G'$.



(a)



(b)