SQG equation on the sphere Analysis seminar, IAS

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Active scalars are a wide class of *transport equations* where the velocity is determined from the transported quantity in a certain way. In this case a temperature  $\theta$  evolves following

$$\begin{cases} \partial_t \theta(x,t) + u(x,t) \cdot \nabla \theta(x,t) = 0, \\ \nabla \cdot u(x,t) = 0 \\ u(x,t) = (-R_2\theta, R_1\theta) \end{cases}$$

where  $R_j$  denotes a Riesz potential

$$R_j(\theta)(x) = \frac{1}{\pi} \int_{\mathbb{R}^2} \frac{y_j}{|y|^3} \theta(x-y) dy$$

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- It models frontogenesis in meteorology ( $\theta$  represents potential temperature).
- It is related to the 3D Euler equation.

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**D. Córdoba.** Provided a proof dismissing such an scenario, Annals of Math. 1998.

In this case we consider

$$\left\{ \begin{array}{l} \theta_t + u \cdot \nabla \theta + \kappa \Lambda^{\alpha} \theta = 0 \\ u = \nabla^{\perp} \Lambda^{-1} \theta \\ \theta(x,0) = \theta_0(x), \kappa > 0 \end{array} \right.$$

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The subcritical case,  $\alpha > 1$ , is well understood (Constantin-Wu, 1998). Global regularity for the critical case  $\alpha = 1$  has been quite more challenging due to the possible balance between opposite strengths of the non-linear and the dissipative terms.

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- Sinite time singularities (even in the compressible case).

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In fact all their proofs work in the n-dimensional tori or euclidean spaces. Our result deals only with the two dimensional sphere, namely:

Alonso-Orán, Córdoba, M. ( $\mathbb{S}^2$ ): Global well-posedness of critical SQG on the sphere, 2018.

Let (M,g) be a compact orientable surface and g be a Riemannian metric the SQG in this case takes the form

$$\begin{cases} \frac{\partial \theta}{\partial t} + u \cdot \nabla_g \theta + \Lambda_g \theta = 0, \\ u = \mathcal{R}_g^{\perp} \theta = \nabla_g^{\perp} \Lambda_g^{-1} \theta \end{cases}$$

where  $\Lambda_g = (-\Delta_g)^{\frac{1}{2}}$  and  $-\Delta_g$  is the Laplace-Beltrami operator.

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Theorem (D. Alonso-Orán, A. Córdoba, A. D. M., 2018)

Let  $\theta_0 \in C^{\infty}(\mathbb{S}^2)$  be the initial datum, then the solution remains smooth for any time t > 0.

## Theorem (D. Alonso-Orán, A. Córdoba, A. D. M., 2018)

Given an initial datum  $\theta_0 \in L^2(\mathbb{S}^2)$  any weak solution becomes instantaneously continuous for any time t > 0.

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## Theorem (D. Alonso-Orán, A. Córdoba, A. D. M., 2018)

There is global well-posedness in  $H^{s}(\mathbb{S}^{2})$  for any s > 3. In fact, any solution with such initial datum becomes smooth instantaneously.

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#### Fractional laplacian basics: euclidean case

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$$\Lambda^{\alpha} f(x) = c_{n,\alpha} P.V. \int_{\mathbb{R}^n} \frac{f(x) - f(y)}{|x - y|^{n + \alpha}} dy,$$
  
$$\Lambda^{\alpha} f(x) = c_{n,\alpha} P.V. \sum_{\nu \in \mathbb{Z}^n} \int_{\mathbb{T}^n} \frac{f(x) - f(y)}{|x - y - \nu|^{n + \alpha}} dy$$

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for any  $0<\alpha<2.$  As an easy consequence of these one can get

#### Theorem (Córdoba-Córdoba inequality)

For any  $\alpha \in (0,2)$  and f smooth enough, the following pointwise inequality holds

$$f(x)\Lambda^{\alpha}f(x) \ge \frac{1}{2}\Lambda^{\alpha}(f^2)(x).$$

Following the trajectories

$$\frac{dx}{dt} = u(x,t)$$

one gets

$$\frac{d}{dt}(\theta(x(t),t)) = \theta_t + \nabla \theta \cdot \frac{dx}{dt} = 0$$

deducing that  $\|\theta(\cdot,t)\|_{L^p}$  remains constant under the evolution  $(1 \le p \le \infty)$ .

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deducing that  $\|\theta(\cdot,t)\|_{L^p}$  remains constant under the evolution  $(1 \le p \le \infty)$ . It is easy to check, using the Córdoba-Córdoba inequality, that the  $L^p$  norms do not increase.

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Theorem (A. Córdoba, A. D. M. 2015)

The following pointwise inequality holds

$$\frac{1}{2m}DN_{\Omega}(f^{2m})(x) \le f(x)^{2m-1}DN_{\Omega}f(x)$$

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 $\ensuremath{\operatorname{PROOF}}$  : To begin with we propose the following Dirichlet problems in the domain

$$\begin{cases} \Delta u = 0 & \text{in } \Omega \\ u = f & \text{in } \partial \Omega \end{cases}$$

and

$$\left\{ \begin{array}{ll} \Delta v = 0 & \mbox{in } \Omega \\ v = f^{2m} & \mbox{in } \partial \Omega \end{array} \right.$$

Then  $w = u^{2m} - v$  satisfies

$$\left\{ \begin{array}{ll} \Delta w = 2m(2m-1)|\nabla u|^2 u^{2m-2} & \text{in } \Omega \\ w = 0 & \text{in } \partial \Omega \end{array} \right.$$

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## The (spectral) fractional Laplace-Beltrami (definition)

The Laplace-Beltrami operator,  $\Delta_g$ , in some local coordinates of the surface (n = 2) takes the form

$$\frac{1}{\sqrt{|g|}} \sum_{i,j=1}^{2} \partial_i \left( \sqrt{|g|} g^{ij} \partial_j \right)$$

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$$-\Delta_g Y_\ell = \lambda_\ell^2 Y_\ell$$

where  $\lambda_0 = 0$  and the eigenvalue increases to infinity as  $\ell \in \mathbb{N}$  increases.

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where  $\lambda_0 = 0$  and the eigenvalue increases to infinity as  $\ell \in \mathbb{N}$  increases. The fractional Laplace-Beltrami operator acts on this basis as  $(-\Delta_g)^{\alpha/2}Y_\ell = \lambda_\ell^\alpha Y_\ell$  and for any other function by linearity. Usual notation is  $\Lambda_g^\alpha = (-\Delta_g)^{1/2}$ .

In the case of a general compact manifold (e.g. a sphere) the above was not available.

Theorem (D. Alonso-Orán, A. Córdoba, A. D. M., 2018)

$$\Lambda_{g}^{\alpha} f(x) = c_{n,\alpha} P.V. \int_{M} \frac{f(x) - f(y)}{d(x, y)^{n+\alpha}} (\chi u_{0} + k_{N})(x, y) \, dy + E$$

where  $k_N(x,y) = O(d(x,y))$  is certain smooth function,  $\chi$  is a diagonal cutoff and the error gains derivatives

$$E = O(||f||_{H^{-N}(M)}).$$

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- Constantin-Vicol improvement with smoothing error.
- Fractional Sobolev embedding theorem for compact manifolds (cf. Aubin).

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Given an initial datum  $\theta_0 \in L^2(\mathbb{S}^2)$  any weak solution becomes instantaneously continuous for any time t > 0.

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- So The argument does not work for dimensions greater than two.

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#### De Giorgi's technique 101

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Lemma (Caccioppoli's (energy) inequality)

Let  $u \ge 0$ ,  $\Delta u \ge 0$  and  $\varphi \in C_0^\infty(B_2)$  then

$$\int_{B_2} |\nabla(\varphi u)|^2(x) dx \le C_{\varphi} \int_{B_2} u^2.$$

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Using Sobolev's embedding and this inequality one can prove

$$E_k \le C2^{2k} E_{k-1}^{1+1/n}$$

where

$$E_k = \int_{B_1} (\varphi_k u_k)^2 dx$$

where  $u_k = (u - (1 - 2^{-k}))_+$  and  $\varphi_k$  is a cut off function on  $B_{1+2^{-k}}.$ 

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where  $u_k = (u - (1 - 2^{-k}))_+$  and  $\varphi_k$  is a cut off function on  $B_{1+2^{-k}}$ . Then  $E_k \to 0$  if  $E_0$  is small enough.

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#### The previous idea can be used, this time

$$E_k = \sup_{t \ge T_k} \int_M \theta_k^2 dx + 2 \int_{T_k}^\infty \int_M |\Lambda^{1/2} \theta_k|^2 dx dt$$

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to show

$$E_k \le C \frac{2^{k(1+2/n)+1}}{t_0 C^{2/n}} E_{k-1}^{1+1/n}.$$

#### Lemma (Local energy inequality, I)

Let  $\theta_k$  satisfy

$$\partial_t \theta_k + u \cdot \nabla_g \theta_k \leq -\Lambda \theta_k$$

and denote  $I(z_0) = [0, z_0]$ . Let the function  $\eta \theta_k^*(x, t, z)$  be vanishing in  $M \times [0, \infty) \setminus B_g(h) \times I(z_0)$ . Then if u satisfies

$$\sup_{t \in (s,t)} \int_{B_g(h)} |u(x,t)|^{2n} dvol_g(x) \le Ch^n$$

and  $s \leq t$ .

## Lemma (Local energy inequality, II)

Then the following holds

$$\begin{split} \int_{s}^{t} \int_{I(z_{0})} \int_{B_{g}(h)} |\nabla_{x,z}(\eta\theta_{k}^{*})(x,t,z)|^{2} dx dz dt + \int_{B_{g}(h)} (\eta\theta_{k})^{2}(x,t) dx \\ & \leq C \left\{ \int_{B_{g}(h)} (\eta\theta_{k})^{2}(x,s) dx + h \int_{s}^{t} \int_{B_{g}(h)} |\nabla_{x}\eta\theta_{k}|^{2} dx dt \\ & + \int_{s}^{t} \int_{I(z_{0})} \int_{B_{g}(h)} |\nabla_{x,z}\eta\theta_{k}^{*}|^{2} dvol_{g}(x) dz dt \\ & + \int_{s}^{t} \int_{B_{g}(h)} (\eta\theta_{k})^{2}(x,t) dvol_{g}(x) dt \right\}. \end{split}$$

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- Nice barrier functions satisfying certain properties (recall no scaling!).
- Very tricky induction argument to get oscillation decay using the above (for small energy).
- Isoperimetric inequality on the sphere (cf. De Giorgi's to get rid of the small energy assumption).
- Rotations to get the logarithmic modulus of continuity.

#### Lemma

Let f be a smooth function on the sphere  $\mathbb{S}^2$  and  $0 < \alpha < 2$ . Then provided that  $|\nabla_g f(x)| \ge C ||f||_{\infty}$  we have the pointwise bound

$$\nabla_g f(x) \cdot \nabla_g \Lambda^{\alpha} f(x) \geq \frac{1}{2} \Lambda^{\alpha} (|\nabla_g f|^2)(x) + \frac{1}{4} D(x) + \frac{|\nabla_g f(x)|^{2+\alpha}}{C \|f\|_{\infty}^{\alpha}} + O(x) + O$$

where D denotes some functional (defined in the proof),  $O = O(||\nabla_g f||_{\infty}^2)$  is an error term and the constant C depends on  $\alpha$  but is independent of x.

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where D denotes some functional (defined in the proof),  $O = O(||\nabla_g f||_{\infty}^2)$  is an error term and the constant C depends on  $\alpha$  but is independent of x.

**Careful:** notice the non commutativity of some operators (despite  $\Psi DO$ ). We need stereographic projection, integral representation with smoothing error.

# Closing the argument (I)

Let 
$$L = (\partial_t + u \cdot \nabla_g + \Lambda_g).$$

$$\frac{1}{2}L(|\nabla_g\theta|^2)(x) + \frac{|\nabla_g\theta(x)|^3}{c\|\theta\|_{\infty}} \leq C|\nabla_g\theta(x)|^2 + O(\|\nabla_g\theta\|_{\infty}^2)$$

holds for any t > 0.

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holds for any t > 0. Evaluating formally at  $\bar{x}$ , a point that reaches the maximum of  $|\nabla_q \theta|(x)$ , one gets

$$\frac{d}{dt}|\nabla_g\theta|^2(\bar{x}) \le 0$$

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Heuristically this prevents indefinite growth for the  $L^{\infty}$  norm of the gradient. This heuristic can be replaced by a honest argument.

From the above it follows that

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in fact, it will be bounded by some absolute constant C > 0.

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in fact, it will be bounded by some absolute constant C > 0. This control is all one needs to prove the theorem thanks to the usual energy estimates.

Theorem (D. Alonso-Orán, A. Córdoba, A. D. M., 2018)

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# Thank you!

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