



# **Contents**

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### **Alternating Minimization - Setup**

**Input:** function

$$f: \mathcal{X}_1 \times \cdots \times \mathcal{X}_d \to \mathbb{R}$$

**Goal**: find **global minimum**  $(x_1^*, ..., x_d^*)$  i.e.

$$f(\mathbf{x}_1^*, \dots, \mathbf{x}_d^*) \simeq \inf_{\substack{x_i \in \mathcal{X}_i \\ 1 \le i \le d}} f(x_1, \dots, x_d)$$

Minimizing f in each block is simple.

That is, for any  $1 \le i \le d$ , given  $(y_1, ..., y_{i-1}, y_{i+1}, ..., y_d)$  easy to solve

$$\inf_{x_i \in \mathcal{X}_i} f(y_1, \dots, y_{i-1}, x_i, y_{i+1}, \dots, y_d)$$

### **Alternating Minimization - Heuristics**

Repeatedly solve basic problem on different coordinates. Start with an initial guess  $y^{(0)}=(y_1^{(0)},\dots,y_d^{(0)})$  and time bound T

- 1. Given vector  $y^{(t)} = \left(y_1^{(t)}, \dots, y_d^{(t)}\right)$ , choose a coordinate  $1 \le i \le d$
- Find

$$z \simeq \underset{x_i \in \mathcal{X}_i}{\arg\inf} f(y_1^{(t)}, \dots, y_{i-1}^{(t)}, x_i, y_{i+1}^{(t)}, \dots, y_d^{(t)})$$

- 4. Set  $y_i^{(t+1)} = z$ , keep all other coordinates **unchanged**
- 5. If t < T go back to step 1.

# AM - product group actions

**Setup:** Group  $G = G_1 \times G_2 \times \cdots \times G_d$  acting on vector space V (for instance  $G_i = SL(n_i), \ V = Ten(n_1, ..., n_d)$ ).  $(A_1, ..., A_d) \cdot X \stackrel{\text{def}}{=} (A_1 \otimes \cdots \otimes A_d)X$ 

**Input:** given  $X \in V$ , function

$$\begin{aligned} f_X \colon G_1 \times \cdots \times G_d &\to \mathbb{R}_{\geq 0} \\ f_X(A_1, \dots, A_d) &= \| (A_1, \dots, A_d) \cdot X \|_2^2 \end{aligned}$$

**Goal**: find elt of min norm in  $\mathcal{O}_G(X)$ , i.e.,  $(A_1^*, ..., A_d^*)$  such that

$$f_X(A_1^*, \dots, A_d^*) \simeq \inf_{\substack{A_i \in G_i \\ 1 \le i \le d}} f_X(A_1, \dots, A_d) \stackrel{\text{def}}{=} cap(X)$$

**Null-cone problem**:  $X \in \mathcal{N}_G(V) \Leftrightarrow \operatorname{cap}(X) = 0$ 

# KN'79 - Duality Theory

**Capacity (primal)**: find elt of min norm in  $\mathcal{O}_G(A)$ , i.e.,  $(A_1^*, ..., A_d^*)$  such that

$$f_X(A_1^*, \dots, A_d^*) \simeq \inf_{\substack{A_i \in G_i \\ 1 \le i \le d}} f_X(A_1, \dots, A_d) \stackrel{\text{def}}{=} cap(X)$$

Moment map 
$$\mu(X)$$
 at  $X \in V$ , define  $h_X : G \to \mathbb{R}_{\geq 0}$  by 
$$h_X(A_1, \dots, A_d) = \left\| \mu \left( (A_1, \dots, A_d) \cdot X \right) \right\|_2^2$$

**Moment map (dual)**: find elt in  $\mathcal{O}_G(X)$ , i.e.,  $(A_1^*, ..., A_d^*)$  that *minimizes norm* of moment map

$$h_X(A_1^*, \dots, A_d^*) \simeq \inf_{\substack{A_i \in G_i \\ 1 \le i \le d}} h_X(A_1, \dots, A_d) \stackrel{\text{def}}{=} cap_{\mu}(X)$$

[KN'79] 
$$cap_{\mu}(X) = 0 \Leftrightarrow cap(X) > 0$$

# Non-Negative Matrices & Scaling

 $X \in \operatorname{Mat}_n(\mathbb{R}_{\geq 0})$  is **doubly stochastic (DS)** if row/column sums of X are equal to 1/n.

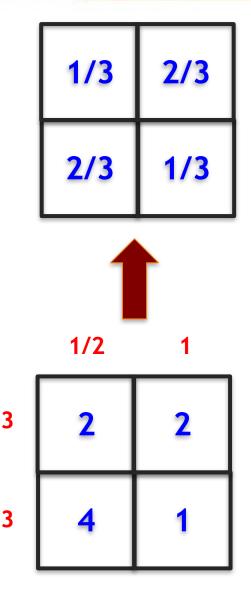
Y is **scaling** of X if  $\exists$  positive  $\alpha_1, ..., \alpha_n, \beta_1, ..., \beta_n$  s.t.  $y_{ij} = \alpha_i x_{ij} \beta_j$ .

X has DS scaling if  $\exists$  scaling Y of X s.t. all row/column sums of Y equal 1/n.

X has approx. DS scaling if  $\forall \epsilon > 0$  there is scaling  $Y_{\epsilon}$  of X s.t. all row/column sums of  $Y_{\epsilon}$  are in  $[1/n - \epsilon, 1/n + \epsilon]$ .



2. Can we find it efficiently?



### Matrix Scaling as null-cone problem

Group  $G = ST(n) \times ST(n)$  acts on  $V = Mat_n(\mathbb{C})$  by

$$\begin{pmatrix} \alpha_1 & 0 & 0 \\ 0 & \ddots & 0 \\ 0 & 0 & \alpha_n \end{pmatrix} \cdot X \cdot \begin{pmatrix} \beta_1 & 0 & 0 \\ 0 & \ddots & 0 \\ 0 & 0 & \beta_n \end{pmatrix}$$

Let 
$$r_i = \frac{1}{\|X\|^2} \sum_j |x_{ij}|^2$$
 and  $c_j = \frac{1}{\|X\|^2} \sum_i |x_{ij}|^2$  be  $X$  "row/column sums".

Moment Map (from Ankit's talk):

$$\mu(X) = \left(r_1 - \frac{1}{n}, \dots, r_n - \frac{1}{n}, c_1 - \frac{1}{n}, \dots, c_n - \frac{1}{n}\right)$$

#### **Dual problem:**

$$ds(X) = \|\mu(X)\|^2 = \sum_{i} \left(r_i - \frac{1}{n}\right)^2 + \sum_{j} \left(c_j - \frac{1}{n}\right)^2$$

X has approx. DS scaling iff  $\forall \epsilon > 0$ ,  $\exists$  scaling  $Y_{\epsilon}$  s.t.  $ds(Y_{\epsilon}) < \epsilon$ .

### Matrix Scaling - Algorithm S

**Problem:**  $X \in Mat_n(\mathbb{C})$ ,  $\epsilon > 0$ , is there  $\epsilon$ -scaling to DS? If yes, find it.

#### Algorithm S [Sinkhorn'64]:

Repeat k times:

- 1. Normalize rows of X (make  $r_i = 1/n$ )
- 2. Normalize columns of X (make  $c_i = 1/n$ )

If at any point  $ds(X) < \epsilon$ , output the scaling so far.

Else, output: no scaling.

#### **Questions:**

- Are we making progress at all?
- How do we know when to stop? (i.e., choose k)
- Is there an  $\epsilon_0$  such that if can scale to  $\epsilon_0$  then can scale for any  $\epsilon$ ?

# **Quantum Operators - Definition**

A quantum operator is any map  $T: M_n(\mathbb{C}) \to M_n(\mathbb{C})$  given by  $(A_1, ..., A_m)$  s.t.

$$T(X) = \sum_{1 \le i \le m} A_i X A_i^{\dagger}$$

Dual of  $\mathbf{T}(\mathbf{X})$  is map  $\mathbf{T}^* \colon \mathbf{M}_n(\mathbb{C}) \to \mathbf{M}_n(\mathbb{C})$  given by:

$$T^*(X) = \sum_{1 \le i \le m} A_i^{\dagger} X A_i$$

 $T: M_n(\mathbb{C}) \to M_n(\mathbb{C})$  is doubly stochastic if  $T(I) = T^*(I) = I$ .

Scaling  $T_{L,R}(X)$  of T(X) consists of  $L,R \in SL(n)$  s.t.

$$(A_1, \ldots, A_m) \rightarrow (LA_1R, \ldots, LA_mR)$$

### **Operator Scaling**

**Moment Map** (from Ankit's talk):

$$\mu(T) = (T(I_n) - \alpha I_n, T^*(I_n) - \alpha I_n), \alpha = tr(T(I_n))/n$$

Distance to doubly-stochastic:

$$ds(T) \stackrel{\text{def}}{=} ||T(I_n) - \alpha I_n||_F^2 + ||T^*(I_n) - \alpha I_n||_F^2$$

T(X) has approx. doubly stochastic scaling if

$$\inf_{T_{L,R}} ds(T_{L,R}) = 0$$

Once again, dual problem is the scaling problem!

- 1. When  $does(A_1, ..., A_m)$  have approx. doubly stochastic scaling?
- 2. Can we find it efficiently?

# Operator Scaling - Algorithm G

**Problem:** operator  $\mathbf{T}=(A_1,\ldots,A_m)$ ,  $\epsilon>0$ , can T be  $\epsilon$ -scaled to double stochastic? If yes, find scaling.

#### Algorithm G [Gurvits' 04]:

Repeat k times:

- 1. Left normalize:  $(A_1, ..., A_m) \leftarrow (RA_1, ..., RA_m)$  s.t.  $T(I) = \alpha I$
- 2. Right normalize:  $(A_1, ..., A_m) \leftarrow (A_1C, ..., A_mC)$  s.t.  $T^*(I) = \alpha I$  If at any point  $\mathbf{ds}(\mathbf{T}) < \epsilon$  output scaling.

Else output **no scaling**.

- Which k should we choose?
- Is there an  $\epsilon_0$  such that if can scale to  $\epsilon_0$  then can scale for any  $\epsilon$ ?

### Tensor Scaling Problem

Let 
$$V = Ten(n_1, ..., n_d)$$
 and  $G = SL(n_1) \times \cdots \times SL(n_d)$ 

 $g = (A_1, ..., A_d) \in \mathbf{G}$  acts on  $X \in V$  in the natural way:

$$g \cdot X = (A_1, \dots, A_d) \cdot X \stackrel{\text{def}}{=} (A_1 \otimes \dots \otimes A_d)X$$

**Goal:** given X, find  $g^* = (A_1^*, ..., A_d^*)$  such that

$$||g^* \cdot X||_2^2 \simeq cap(X) \stackrel{\text{def}}{=} \inf_{g \in G} ||g \cdot X||_2^2$$

**Null-cone Problem:** cap(X) = 0

Moment map (dual) Problem?

# Quantum Setting (Previous talks)

Tensor  $X \in Ten(n_1, ..., n_d)$  is **pure quantum state\***, can be written as  $\rho = XX^{\dagger} = |\psi\rangle\langle\psi|$ .

• PSD matrix, dim  $n = n_1 \cdots n_d$ ,  $tr(\rho) = ||X||^2$ .

Let  $\rho_i$  be **marginal** of  $\rho$  with respect to particle i.

• PSD matrix, dim  $n_i$ ,  $tr(\rho_i) = ||X||^2$ .

ho d-stochastic (locally maximally entangled) if all  $ho_i \propto I_{n_i}$ 

**Quantum distillation:** given pure state  $\rho$ , is there a scaling of  $\rho$  into a d-stochastic state?

Moment map (from Ankit's talk):

$$\mu(X) = \left(\frac{1}{\|X\|^2} \rho_1 - \left(\frac{1}{n_1}\right) I_{n_1}, \cdots, \frac{1}{\|X\|^2} \rho_d - \left(\frac{1}{n_d}\right) I_{n_d}\right)$$

**Dual Problem:** 
$$ds(X) = \|\mu(X)\|^2 \to dds(X) = \inf_{Y \in \mathcal{O}(X)} ds(Y)$$

# Tensor Scaling - Algorithm

**Problem:**  $X \in Ten(n_1, ..., n_d)(\mathbb{Z}[i])$ ,  $\epsilon > 0$ , is there  $\epsilon$ -scaling to DS? If yes, find it.

#### Algorithm Q [BGOWW'18]:

Start with input X and scaling  $(I_{n_1}, ..., I_{n_d})$ 

Repeat k times:

- 1. If  $ds(X) < \epsilon$ , output the scaling so far.
- 2. Let i be marginal s.t.  $\left\| \frac{1}{\|X\|^2} \rho_i \frac{1}{n_i} I_{n_i} \right\|^2 > \frac{\epsilon}{n}$
- 3. Normalize  $\rho_i$  (make  $\rho_i = I_{n_i}$ )

Output: no scaling.

#### **Questions:**

- How do we know when to stop? (i.e., choose k)
- Is there an  $\epsilon_0$  such that if can scale to  $\epsilon_0$  then can scale for any  $\epsilon$ ?

### **Analysis - General Approach**

#### Three steps:

- **1.** [Upper bound] in beginning  $||X||^2 \le poly(n, 2^b)$ 
  - Trivial from input data
- **2.** [Progress/step] If  $ds(X) > \epsilon$  (i.e., far from solution to dual) then normalization decreases  $||X||^2$  by factor  $\times \exp(O(\epsilon/n))$  (i.e., makes progress in primal)
  - Quantitative AM-GM (easy)
- 3. [Lower bound]  $cap(X) > 0 \Rightarrow cap(X) > 1/n^2$ 
  - Invariant polynomials generated by nice poly. (hard)

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\epsilon-scaling problem \rightarrow running time of poly(nb/\epsilon). Solve null-cone prb:
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Matrix/Operator scaling:  $\epsilon = O(1/n)$  is enough [Gur'04] Tensor scaling:  $\epsilon = \exp(-n \log n)$  [HM, NM'84, BGOWW'18]

# Algorithm S - Analysis [LSW'00\*]

#### Algorithm S [Sinkhorn'64]:

Repeat k times:

- 1. Normalize rows of X (make  $r_i = 1/n$ )
- 2. Normalize columns of **X** (make  $c_i = 1/n$ )

If at any point  $ds(X) < \epsilon$ , output the scaling so far.

Else, output: no scaling.

#### Analysis [LSW'00\*]:

- 1.  $||X||^2 \le poly(n, 2^b)$  as X is integer bit comp. b
- 2.  $ds(X) > \epsilon \Rightarrow ||X||^2$  shrinks by  $exp(O(\epsilon/n))$  after normlyting
- 3.  $Per(\widehat{Y}) \ge 1$  for any matrix Y in orbit of  $X \Rightarrow ||Y||^2 \ge 1/n^2$

Within  $\mathbf{k} = poly(nb/\epsilon)$  iterations we will get our scaling!

If  $Per(\hat{X}) > 0 \Leftrightarrow X$  has no Hall blocker, so it is correct.

 $\operatorname{Per}(\widehat{X})$  not needed, as any monomial encoding matching\*\* works.

# Algorithm G - Analysis [GGOW'16]

#### Algorithm G [Gurvits' 04]:

#### Repeat k times:

- 1. Left normalize:  $(A_1, ..., A_m) \leftarrow (RA_1, ..., RA_m)$  s.t. T(I) = I.
- 2. Right normalize:  $(A_1, \ldots, A_m) \leftarrow (A_1C, \ldots, A_mC)$  s.t.  $T^*(I) = I$ . If at any point  $\mathbf{ds}(\mathbf{T}) < \epsilon$  output scaling.

Else output **no scaling**.

#### Analysis [GGOW'16]:

- 1.  $||T||^2 \le poly(n, 2^b)$  as  $A_i$  is integer bit comp. b
- 2.  $ds(T) > \epsilon \Rightarrow ||X||^2$  shrinks by  $exp(O(\epsilon/n))$  after normlytin
- 3.  $P(T_{L,R}) \ge 1$  for any  $T_{L,R}$  in orbit of  $T \Rightarrow \|T_{L,R}\|^2 \ge 1/n^2$

Within  $\mathbf{k} = poly(nb/\epsilon)$  iterations we will get our scaling!

 Is there an ε<sub>0</sub> such that if can scale to ε<sub>0</sub> then can scale for any ε?

# Algorithm Q - Analysis [BGOWW'18]

**Problem:**  $X \in Ten(n_1, ..., n_d)(\mathbb{Z}[i]), \epsilon > 0$ , is there  $\epsilon$ -scaling to DS?  $n = n_1 n_2 \cdots n_d$ .

#### **Analysis:**

- 1.  $||X||^2 \le poly(n, 2^b)$  as X is integer bit comp. b
- 2.  $ds(X) > \epsilon \Rightarrow ||X||^2$  shrinks by  $exp(O(\epsilon/n))$  after normlztn
- 3.  $P(Y) = P(X) \ge 1$  for any  $Y \in \overline{\mathcal{O}(X)} \Rightarrow ||Y||^2 \ge 1/n^2$

Within  $\mathbf{k} = poly(nb/\epsilon)$  iterations we will get our scaling!

#### Step 3:

Invariant ring  $\mathbb{C}[X]^G$  generated by polys of:

- 1. degree  $\leq 2^{n^2}$  [Derksen'01]
- 2. Integer coefficients of norm  $\leq poly(n)$  [Pro'07, BI'13,BGOWW'18]\*

$$P(X) > 0$$
,  $deg(P) = m \Rightarrow P(X) \ge 1 \Rightarrow ||X||^m \cdot n^{2m} \ge 1$ 

#### Choosing $\epsilon$ for Null-cone problem

Problem:  $X \in Ten(n_1, ..., n_d)(\mathbb{Z}[i])$ , is  $X \in \mathcal{N}_G(V)$ ?

#### Algorithm Q [BGOWW'18]:

Start with input X and scaling  $(I_{n_1}, ..., I_{n_d})$ 

Repeat k times:

- 1. If  $ds(X) < \epsilon$ , output the scaling so far.
- 2. Let i be marginal s.t.  $\left\| \frac{1}{\|X\|^2} \rho_i \frac{1}{n_i} I_{n_i} \right\|^2 > \frac{\epsilon}{n}$
- 3. Normalize  $\rho_i$  (make  $\rho_i = I_{n_i}$ )

Output: **no scaling.** 

#### Which $\epsilon$ should we choose?

- 1. [Mum'65] Instability parameter for tensor "how quickly can we drive tensor to zero"
- 2. [NM'84] Instability lower bounds ds(X) for any X
- 3. Bound on instability (bound soln to LP) implies ds(X) l.b.

#### Instability and ds(X) lower bound

[HM]: 
$$X \in \mathcal{N}_G(V) \Leftrightarrow 1$$
-PSG  $\lambda : \mathbb{C}^{\times} \to G$  s.t.  $\lim_{t \to 0} \lambda(t) X = 0$ 

[Mum'65]: how quickly does it go to zero?

$$\lambda(t) \leftarrow \left(B_i^{-1} \operatorname{diag}(t^{a_{i1}}, \cdots, t^{a_{in}})B_i\right)_{i=1}^d,$$
 $B_i \in U(n_i), a_{ij} \in \mathbb{Z}, \sum_{j=1}^n a_{ij} = 0$ 

- 1.  $supp((B_1, \dots, B_d) \cdot X) \stackrel{\text{def}}{=} set of nonzero entries$
- 2. If for every  $(j_1, \dots, j_d)$  in support,  $\sum a_{ij_i} > 0$  then  $\lambda(t)X \to 0$

3. Instability 
$$\mathbf{inst}(\lambda, \mathbf{X}) = \min_{(j_1, \dots, j_d) \in supp} \frac{\sum a_{ij_i}}{\sqrt{\sum a_{ij}^2}}$$

$$inst(X) = \max_{\lambda \text{ 1PSG}} inst(\lambda, X)$$

Given 1-PSG  $\lambda: \mathbb{C}^{\times} \to G$  s.t.  $\lim_{t\to 0} \lambda(t) X = 0$  how to l.b.  $\operatorname{inst}(\lambda, X)$ 

#### Instability and ds(X) lower bound

1-PSG 
$$\lambda$$
 s.t.  $\lim_{t\to 0}\lambda(t)\,X=0\Rightarrow$  following LP has soln

$$a_{ij} \in \mathbb{Q}$$
 ,  $\sum_{j=1}^n a_{ij} = 0 \ orall i \in [d]$  ,

$$\sum_{i=1}^d a_{ij_i} \geq \mathbf{1} \ orall (j_1, ..., j_d)$$
 in support

Thus, has soln bounded by  $\exp(-n \cdot \log(n))$  [Sch'98]

How does inst(X) l.b. ds(X)?

Easy calculation shows that for any  $(a_{ij})$ 

$$\min_{(j_1,\ldots,j_d)\in supp(X)} \frac{\sum a_{ij_i}}{\sqrt{\sum a_{ij}^2}} \leq \sqrt{ds(X)} = \sqrt{ds\big((U_1,\ldots,U_d)\cdot X\big)}$$

[NM'84]: this holds more general group actions

Thus  $ds(X) \ge inst(X)^2 \ge exp(-2n \cdot log(n))$ .

# Matrix and operator scaling

1-PSG 
$$\lambda$$
 s.t.  $\lim_{t\to 0} \lambda(t) X = 0 \Rightarrow$  following LP has soln

$$a_{ij} \in \mathbb{Q}$$
 ,  $\sum_{j=1}^n a_{ij} = \mathbf{0} \ orall i \in [d]$  ,

$$\sum_{i=1}^d a_{ij_i} \geq \mathbf{1} \ orall (j_1, ..., j_d)$$
 in support

Thus, has soln bounded by  $\exp(-n \cdot \log(n))$  [Sch'98]

How can we better lower bound inst(X) in Matrix/Operator Scaling?

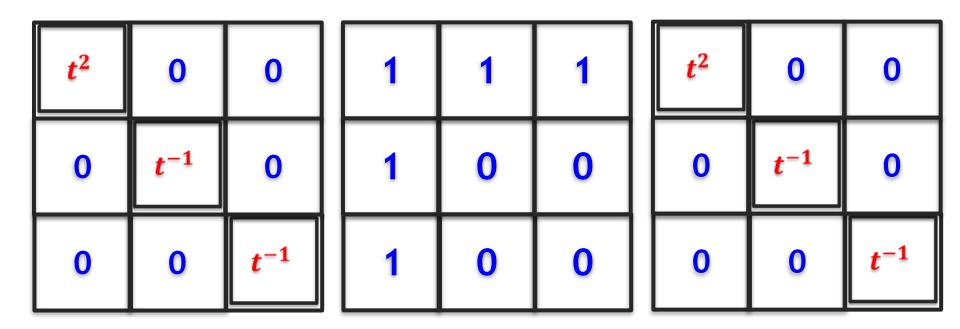
Construct a small solution  $(a_{ij})$  to

$$\min_{(j_1,\ldots,j_d)\in supp(X)} \frac{\sum a_{ij_i}}{\sqrt{\sum a_{ij}^2}}$$

**Hint:** use Hall blocker to find small solution.

Thus in these cases:  $ds(X) \ge inst(X)^2 \ge 1/n^2$ .

# Example - Matrix scaling



Common Hall blocker (shrunk subspace) in operator scaling yields same bound.

### Non-uniform marginals [BFGOWW'18]

Tensor  $X \in \mathbb{P}(Ten(n_1, ..., n_d))$  is **pure quantum state**, can be written as  $\rho = XX^{\dagger}/X^{\dagger}X = |\psi\rangle\langle\psi|$ . Group  $G = GL(n_1) \times \cdots \times GL(n_d)$ 

Quantum marginal problem: given pure state X, target marginals  $\rho_1, \dots, \rho_d$ , (unit trace) is there a scaling of X with such marginals?

(Michael's talk): membership in moment/entanglement polytope of X  $p_i = spec(\rho_i), p \in \Delta(X)$ 

Natural attempt: is there another representation where the moment maps for image of  $X \in Ten(n_1, ..., n_d)$  is given by  $\rho_i^X - p_i$ ?

**Shifting trick** (from Michael's talk):  $p=(p_1,\dots,p_d)$  spectrum of marginals,  $p_i=\ell_i/k$  then  $Y\stackrel{\text{def}}{=} X^{\bigotimes k} \bigotimes v_{\ell^*}$  is such that

$$\mu(Y) = k \cdot \mu(X) + \mu(v_{\ell^*}) = k\mu(X) + \ell^* = (\rho_i^X - p_i)_{i=1}^d$$

Reduces arbitrary marginal problem to uniform case!\*

# Non-uniform Tensor Scaling - Algorithm

**Problem:**  $X \in Ten(n_1, ..., n_d)(\mathbb{Z}[i])$ ,  $\epsilon > 0$ ,  $p_1, ..., p_d$  target spectra. Is there  $\epsilon$ -scaling to  $p_1, ..., p_d$ ? If yes, find it.

#### Algorithm Q+ [BFGOWW'18]:

Start with input X and random scaling  $g = (A_1, ..., A_d)$ Repeat T times:

- 1. If  $ds_p(X) < \epsilon$ , output the scaling so far.
- 2. Let i be marginal s.t.  $\left\|\frac{1}{\|X\|^2} \rho_i p_{i\uparrow}\right\|^2 > \frac{\epsilon}{n}$
- 3. Normalize  $\rho_i$ 
  - 1.  $ho_i \leftarrow p_{i\uparrow}^{-1/2} R_i$ , where  $R_i R_i^\dagger = 
    ho_i$
  - 2.  $R_i$  upper triangular (Borel)

Output: no scaling.

### Analysis - General Marginals

#### Three steps:

- **1.** [Upper bound] in beginning  $||g_0 \cdot X||^2 \le poly(n, k, 2^b)$ 
  - Need  $g_0$  for HWV not to vanish w.h.p. (Michael's talk)
    - Need degree bounds on HWV to show that  $g_0$  is nice
- **2.** [Progress/step] If  $ds(Y) > \epsilon$  (i.e., far from solution to dual) then normalization decreases  $||Y||^2$  by factor  $\times \exp(O(\epsilon/n))$  (i.e., makes progress in primal)
  - Quantitative AM-GM (easy)
  - Scale by Borel to keep HWV invariant under scaling
- 3. [Lower bound]  $cap_p(X) > 0 \Rightarrow cap_p(X) > 1/n^2$ 
  - HWVs are generated by nice poly. (hard)

# Thank you!