Do NP-Hard Problems Require Exponential Time?

Andrew Drucker

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April 8, 2014

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NP and the ETH

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• 3-SAT, 3-Coloring, Hamilton Path NP-complete.



NP and the ETH

• Want to solve NP-complete problems \implies must accept compromise!

- Popular approach: find approximately-optimal solutions. (for optimization probs.)
- Here too, NP-completeness theory (+ PCPs) often provides great guidance!
 - ▶ .5-approx Max-LIN $(\mathbb{F}_2) \in \mathsf{PTIME};$
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Known results for some popular NP-C problems:

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HAM. PATH		<i>n</i> !	2^n , 1.7^n	[Held, Karp '62; Bjorklund '10]

(Strictly: F(n)'s above should be $O^*(F(n)) \triangleq F(n) \cdot |instance|^{O(1)}$.)

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• Given: a k-CNF $\mathcal{F} = C_1 \wedge C_2 \wedge \ldots \wedge C_m$.

(each C_i an OR of $\leq k$ literals)

• Goal: find a satisfying solution to \mathcal{F} if one exists.

Algorithm $A(\mathcal{F})$:

- Let $x \leftarrow (random assignment)$.
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- **Bepeat** Step 2 for 3n steps.

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Or Repeat Step 2 for **3***n* steps.

Suppose \$\mathcal{F}(x^*) = 1\$. Let \$x^t = state of \$x\$ after \$t\$ execs. of Step 2. Let

$$Y_t \triangleq ||x^t - \mathbf{x}^*||_1$$
.

• Key fact: if $Y_t > 0$, then $\Pr[Y_{t+1} = Y_t - 1] \ge 1/k$.

• Can lower-bound $Pr[min_t Y_t = 0]$ in terms of a <u>biased random walk</u>. (biased against us, but not too badly!

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Challenge for complexity theory:	explain the seeming differences in difficulty!
	Identify barriers to further progress!
	Guide search for faster algorithms!

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- No idea. Seems hopeless!
- Influential approach: strengthen the conjecture!

Exponential Time Hypothesis—informal (Impagliazzo, Paturi, Zane '98) No $2^{o(n)}$ -time algorithm for n-variable 3-SAT.

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• Formally: for $k \ge 3$, define $s_k \in [0, 1]$ by

 $s_k \triangleq \inf \{ \varepsilon : k \text{-SAT decidable in time } O^*(2^{\varepsilon n}) \}$

(allowing randomized algs with 1/3 error prob.)

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• $s_3 \leq s_4 \leq s_5 \leq \ldots$

• Best known: $s_3 \leq .388$, $s_4 \leq .555$, $s_k \leq 1 - \Theta(1/k)$. [Paturi, Pudlák, Saks, Zane '98; Hertli '11]

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• Issue: ETH studies dependence on key param.

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- Consider IND. SET problem. Solvable in O^{*}(1.23^N) time on N-vertex graphs.
- Can we hope for $2^{o(N)}$? Or, would that violate ETH?
- Given: $2^{o(N)}$ -time alg for **IND. SET**; try to solve **3-SAT** instance \mathcal{F} . ($n \triangleq \#$ vars, $m \triangleq \#$ clauses)
- Usual NP-C reduction: $\mathcal{F} \longrightarrow (G, k)$, where $|V(G)| = \Theta(n+m) = \Theta(m)$.

•
$$\implies$$
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WEAK!

• $2^{o(N)}$ time alg for IND. SET \implies Solve 3-SAT in time $2^{o(m)}$.

Solve k-SAT in time $2^{o(m)} \implies$ Solve k-SAT in time $2^{o(n)}$!!

• So, $2^{o(N)}$ time alg for **IND. SET** violates **ETH**.

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- Similar: HAM PATH, DOMINATING SET, VERTEX COVER.

• Planar IND. SET problem:

Solvable in $2^{O(\sqrt{N})}$ time on *N*-vertex planar graphs.

• Can we hope for $2^{o(\sqrt{N})}$?

• Usual NP-C reduction: 3-CNF $\mathcal{F} \longrightarrow (\text{planar}) (G, k)$, where $|V(G)| = \Theta(m^2)$.

• Solve Planar IND SET in time $2^{o(\sqrt{N})} \implies$ solve 3-SAT in time $2^{o(m)}$. Again, violates ETH!

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• Why focus on **3-SAT**? Is it WLOG?

• Usual NP-C reduction maps $\mathcal{F}^{(4)} \longrightarrow \mathcal{G}^{(3)}$, where $\# \operatorname{vars}(\mathcal{G}^{(3)}) = \Theta(\# \operatorname{clauses}(\mathcal{F}^{(3)}))$.

• $2^{o(n)}$ time alg for **3-SAT** \implies Solve **4-SAT** in time $2^{o(m)}$. ([IPZ] result, again) \implies Solve **4-SAT** in time $2^{o(n)}$!

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 $s_k \triangleq \inf \{ \varepsilon : k \text{-SAT decidable in time } O^*(2^{\varepsilon n}) \}$.

Exponential Time Hypothesis (**ETH**) (IPZ'97) $s_3 > 0$.

Best known: $s_k \leq 1 - \Theta(1/k)$. Why not "go for broke?"

Strong Exp. Time Hypothesis (**SETH**) (IP'98) $\lim_{k} s_{k} = 1.$

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More consequences of ETH, SETH

- Many more runtime LBs shown under ETH, SETH.
- Strong power to explain dependence on natural input parameters.
- Major implications for parametrized complexity theory
 [Downey, Fellows]; [Lokshtanov, Marx, Saurabh survey]
- Many problem instances have associated integer parameter gives some indication of difficulty.
- E.g., VERTEX COVER:

Given: (G, k)**Decide:** does *G* have a vertex cover of size *k*?

 Goal of "parametrized algorithm" design: design algs that are "fast when k is small."

• VERTEX COVER:

Given: (*G*, *k*) **Decide:** does *G* have a vertex cover of size *k*?

• Known: VERTEX COVER solvable in time $2^k \cdot n^{O(1)}$

• **ETH implies**: Can't solve in time $2^{o(k)} \cdot n^{O(1)}$.

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• CLIQUE:

Given: (G, k)

Decide: does G have a clique of size k?

- Known: CLIQUE solvable in time $\approx n^k/k!$ (n = # verts).
- Standard assumption (FPT \neq W[1]) implies:

can't solve in $F(k) \cdot n^{O(1)}$...

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• <u>k-DOMINATING SET:</u>

Given: graph *G*. **Decide:** does *G* have a dom. set of size *k*?

• Known: solvable in time $n^{k+o(1)}$.

[Eisenbrand, Grandoni'04; Pătrașcu, Williams'10]

• **Strong ETH implies**:* Can't solve in time $n^{k-\varepsilon}$.

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- **Treewidth** of a graph G: tw(G) = measure of "fatness" of G.
- Known: many NP-C graph problems solvable fast on low-treewidth graphs (by dynamic prog.), in time*

 $c^{tw(G)} \cdot n^{O(1)}$ for some c.

*(Given a tree decomposition.)

• [Lokshtanov, Marx, Saurabh '11]: **Strong ETH** \implies some of these algorithms are **optimal!**

(constant *c* can't be improved!)

E.g., IND SET, MAX-CUT: c = 2, DOM. SET: c = 3

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How well can we approximate IND SET on *n*-vertex graphs in subexponential time?

Consider obtaining an *r*-approximation to max ind. set size, $r = r(n) = \omega(1)$.

Theorem (Chitniz, Hajiaghayi, Kortsarz'13) Can get r-approximation in time $O^*(2^{n/r})$.

Theorem (Chalermsook, Laekhanukit, Nanongkai) Under **ETH**, no alg. for $r(n) < n^{.49}$ can have runtime $O^*(2^{n^{.99}/r^{1.01}})$.

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If we can estimate diameter(G) to approx. factor $(3/2 - \varepsilon)$ in time $O(m^{2-\delta})$, then **SETH** fails.

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Andrew Drucker (IAS)

Further afield

- [Abboud, Vassilevska Williams'14]: Improvements in certain dynamic algorithms for graph problems ⇒ ¬SETH.
- [Bringmann, this morning]: Compute <u>Fréchet distance</u> in $n^{2-\varepsilon}$ time $\Rightarrow \neg$ SETH.
- Seems likely to see more results of this kind...

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Theorem (IPZ) **k-SAT** in time $O^*(2^{\varepsilon m}) \ \forall \varepsilon > 0 \implies \text{k-SAT}$ in time $O^*(2^{\varepsilon n}) \ \forall \varepsilon > 0$.

 $m = \# \operatorname{clauses}(\mathcal{F}), \qquad n = \# \operatorname{variables}(\mathcal{F}).$

• Let's see the proof ideas. Main challenge: for general "dense" \mathcal{F} , may have $m \gg n$.

• Ideal approach: give a "sparsification" reduction:

 $\mathcal{F} \longrightarrow^{ptime} \mathcal{F}' \qquad SAT(\mathcal{F}) = SAT(\mathcal{F}')$ $m', n' \leq O(n).$

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$$\mathcal{F} \rightarrow^{2^{o(n)} time} \mathcal{G}^1, \mathcal{G}^2, \dots, \mathcal{G}^s \qquad s = 2^{o(n)}$$

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Sparsification Lemma (IPZ'97)

Fix $k \geq 3, \varepsilon > 0$.

There exists a reduction $\mathcal{F} \to \mathcal{G}^1, \ldots, \mathcal{G}^s$, computable in time $O^*(2^{\varepsilon n})$, such that

- $\mathcal{F} \in SAT$ iff $\exists i : \mathcal{G}^i \in SAT$;
- 2 $s \leq 2^{\varepsilon n};$
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Proof of sparsification lemma

(debt to D. Scheder's notes!)

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Andrew Drucker (IAS)

NP and the ETH

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Thanks!

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