

Cylindrical contact homology as a well-defined homology?

Jo Nelson

Columbia University and the IAS

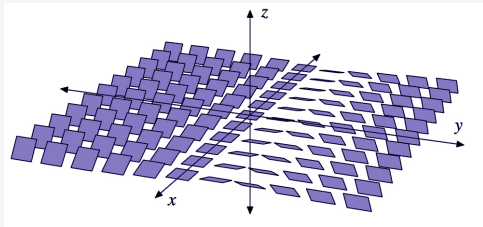
IAS, September 30, 2013

What is a contact manifold?

A **contact structure** ξ on M^{2n-1} is a maximally non-integrable hyperplane distribution...

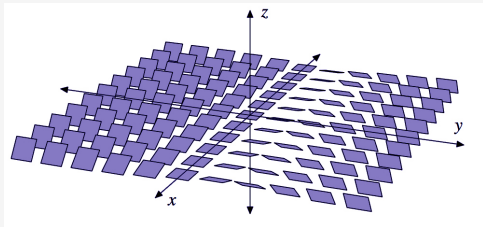
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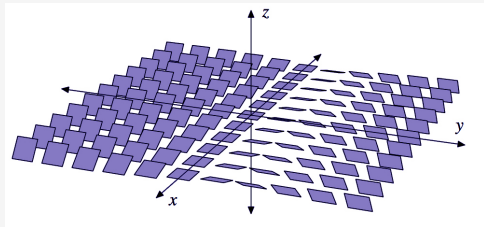
If α is a 1-form on M and

- $\alpha \wedge (d\alpha)^{n-1}$ is a volume form
- $\Leftrightarrow d\alpha|_{\xi}$ is nondegenerate

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Above:

$$\alpha = dz - ydx$$

Choose a contact form α .

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The Reeb vector field R_α is uniquely determined by

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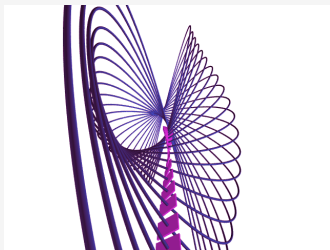
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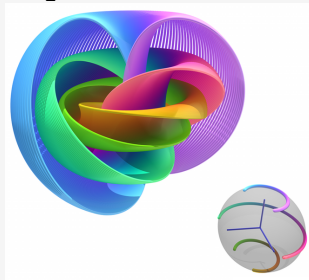
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<http://www.nilesjohnson.net/hopf.html>

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Assume: M compact and α nondegenerate

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“Do” Morse theory on

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- $C_*(\alpha) = \{\text{closed Reeb orbits}\} \setminus \{\text{bad Reeb orbits}\}$

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- Hope this is independent of our choices.

Conjeorem (Eliashberg-Givental-Hofer '00)

Assume a minimal amount of things. Then $(C_(\alpha), \partial)$ forms a chain complex and $H(C_*(\alpha), \partial)$ is independent of α and \tilde{J} .*

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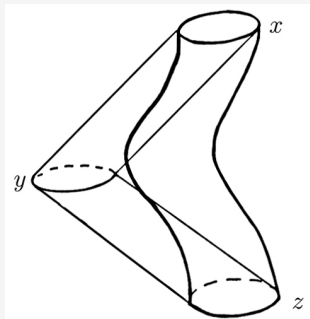
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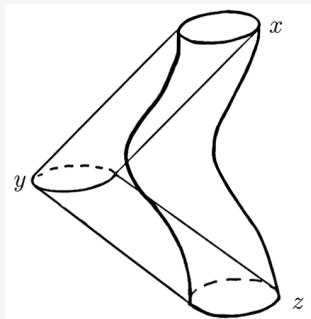
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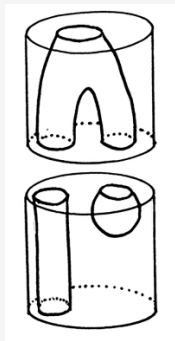
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Adding to 2 becomes hard

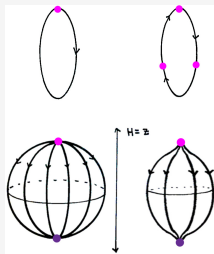
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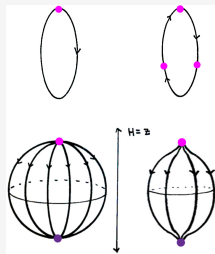
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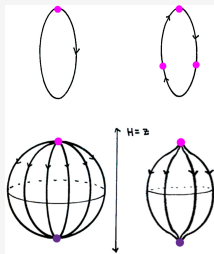
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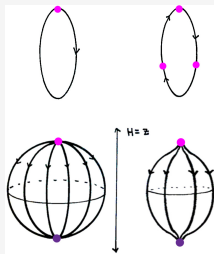


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- (i) All closed simple contractible Reeb orbits γ satisfy $3 \leq \mu_{CZ}(\gamma) \leq 5$.

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- $\mu_{CZ}(\gamma^k) = \mu_{CZ}(\gamma^{k-1}) + 4$, γ^k is the k -th iterate of a simple orbit γ .

Links of simple singularities

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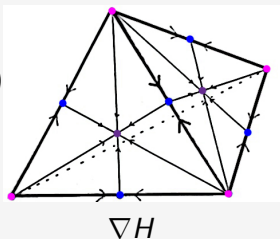
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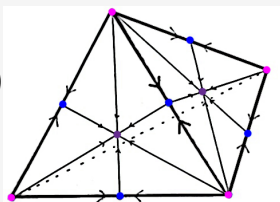
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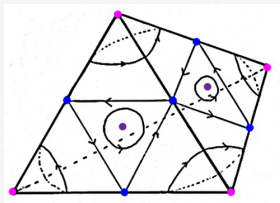
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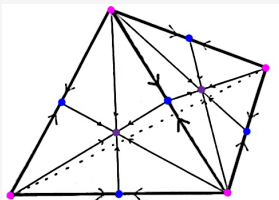
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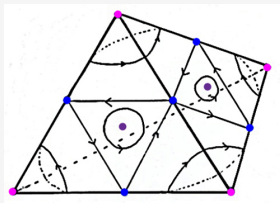
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X_H

Reeb orbits which generate chain complex correspond to presentation of S^3/Γ as a Seifert fiber space!

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- Other dynamical questions involving contact structures

Thanks!