# Sum-product estimates for well-conditioned matrices 

J. Solymosi and V. Vu<br>Dedicated to the memory of György Elekes


#### Abstract

We show that if $\mathcal{A}$ is a finite set of $d \times d$ well-conditioned matrices with complex entries, then the following sum-product estimate holds $|\mathcal{A}+\mathcal{A}| \times|\mathcal{A} \cdot \mathcal{A}|=\Omega\left(|\mathcal{A}|^{5 / 2}\right)$.


## 1. Introduction

Let $\mathcal{A}$ be a finite subset of a ring $Z$. The sum-product phenomenon, first investigated by Erdős and Szemerédi [4], suggests that either $\mathcal{A} \cdot \mathcal{A}$ or $\mathcal{A}+\mathcal{A}$ is much larger than $\mathcal{A}$. This was first proved for $\mathbb{Z}$, the ring of integers, in [4]. Recently, many researchers have studied (with considerable success) other rings. Several of these results have important applications in various fields of mathematics. The interested readers are referred to Bourgain's survey [1].
In this paper we consider $Z$ being the ring of $d \times d$ matrices with complex entries. (We are going to use the notation 'matrix of size $d$ ' for $d \times d$ matrices.) It is well known that one cannot generalize the sum-product phenomenon, at least in the straightforward manner, in this case. The archetypal counterexample is the following:

Example 1.1. Let $I$ denote the identity matrix and let $E_{i j}$ be the matrix with only one nonzero entry at position $i j$ and this entry is one. Let $M_{a}:=I+a E_{1 d}$ and let $\mathcal{A}=\left\{M_{1}, \ldots, M_{n}\right\}$. It is easy to check that $|\mathcal{A}+\mathcal{A}|=|\mathcal{A} \cdot \mathcal{A}|=2 n-1$.

This example suggests that one needs to make some additional assumptions in order to obtain a non-trivial sum-product estimate. Chang [2] proved the following

Theorem 1.2. There is a function $f=f(n)$ tending to infinity with $n$ such that the following holds. Let $\mathcal{A}$ be a finite set of matrices of size $d$ over the reals such that for any $M \neq M^{\prime} \in \mathcal{A}$, we have $\operatorname{det}\left(M-M^{\prime}\right) \neq 0$. Then we have

$$
|\mathcal{A}+\mathcal{A}|+|\mathcal{A} \cdot \mathcal{A}| \geqslant f(|\mathcal{A}|)|\mathcal{A}| .
$$

The function $f$ in Chang's proof tends to infinity slowly. In most applications, it is desirable to have a bound of the form $|\mathcal{A}|^{1+c}$ for some positive constant $c$. In this paper, we show that this is indeed the case (and in fact $c$ can be set to be $\frac{1}{4}$ ) if we assume that the matrices are far from being singular. Furthermore, this result provides a new insight into the above counterexample (see the discussion following Theorem 2.2).

[^0]Notation. We use asymptotic notation under the assumption that $|\mathcal{A}|=n$ tends to infinity. Notation such as $f(n)=\Omega_{\xi}(m)$ means that there is a constant $c>0$, which depends on $\xi$ only, such that $f(n) \geqslant c m$ for every large enough $n$. Throughout the paper letter $\xi$ might be a number like $d$ or a vector like $\kappa, d$ or $\alpha, r$. The notation $f(n)=\mathrm{O}_{\xi}(m)$ means that there is a constant $c$, which depends on $\xi$ only, such that $f(n) \leqslant c m$ for every large enough $n$. In both cases $m$ is a function of $n$ or it is the constant one function, $m=1$, in which case we write $\Omega_{\xi}(1)$ or $\mathrm{O}_{\xi}(1)$. Throughout the paper symbol $\mathbb{C}$ denotes the field of complex numbers.

## 2. New results

The classical way to measure how close a matrix is to being singular is to consider its condition number.

For a matrix $M$ of size $d$, let $\sigma_{\max }(M)$ and $\sigma_{\min }(M)$ be the largest and smallest singular values of $M$. The quantity $\kappa(M)=\sigma_{\max }(M) \sigma_{\min }(M)^{-1}$ is the condition number of $M$. (If $M$ is singular, then $\sigma_{\min }(M)=0$ and $\kappa(M)=\infty$.)

Our main result shows that if the matrices in $\mathcal{A}$ are well conditioned (that is, their condition numbers are small, or equivalently they are far from being singular), then $|\mathcal{A}+\mathcal{A}|+|\mathcal{A} \cdot \mathcal{A}|$ is large.

Definition 2.1. Let $\kappa$ be a positive number at least one. A set $\mathcal{A}$ of matrices is called $\kappa$-well conditioned if the following conditions hold.
(i) For any $M \in \mathcal{A}$, we have $\kappa(M) \leqslant \kappa$.
(ii) For any $M, M^{\prime} \in \mathcal{A}$, we have $\operatorname{det}\left(M-M^{\prime}\right) \neq 0$, unless $M=M^{\prime}$.

Theorem 2.2. Let $\mathcal{A}$ be a finite $\kappa$-well-conditioned set of size $d$ matrices with complex entries. Then we have

$$
|\mathcal{A}+\mathcal{A}| \times|\mathcal{A} \cdot \mathcal{A}| \geqslant \Omega_{\kappa, d}\left(|\mathcal{A}|^{5 / 2}\right)
$$

Consequently, we have

$$
|\mathcal{A}+\mathcal{A}|+|\mathcal{A} \cdot \mathcal{A}| \geqslant \Omega_{\kappa, d}\left(|\mathcal{A}|^{5 / 4}\right)
$$

Theorem 2.2 is a generalization of the first author's sum-product bound on complex numbers [ $\mathbf{7}]$. Some elements in the proof of Theorem 2.2 were inspired by techniques applied in [7]. The idea of using geometry for sum-product problems was introduced by Elekes [3].

REMARK 2.3. By following the proof closely, one can set the hidden constant in $\Omega$ as $\left(\frac{c}{\kappa}\right)^{d^{2}}$, where $c$ is an absolute constant $\left(\frac{1}{100}\right.$, say, would be sufficient).

REmark 2.4. We reconsider the set in the counterexample. It is easy to show that both $\sigma_{\max }\left(M_{a}\right)$ and $\sigma_{\min }\left(M_{a}\right)^{-1}$ are $\Omega_{d}(a)$. Thus $\kappa\left(M_{a}\right)=\Omega_{d}\left(a^{2}\right)$, which, for a typical $a$, is $\Omega_{d}\left(|\mathcal{A}|^{2}\right)$. Hence, the matrices in the counterexample have very large condition numbers.

REMARK 2.5. Note that if the entries of a matrix $M$ of size $d$ are random integers from $\{-n, \ldots, n\}$, then, with probability tending to one as $n$ tends to infinity, $\kappa(M)=\mathrm{O}_{d}(1)$. (In order to see this, note that by Hadamard's bound, $\sigma_{\max }(M) \leqslant d n$ with probability one. Moreover, it is easy to show that with high probability $|\operatorname{det} M|=\Omega_{d}\left(n^{d}\right)$, which implies that $\left.\sigma_{\min }(M)=\Omega_{d}(n).\right)$

The proof of Theorem 2.2 is presented in Sections 3-6.

## 3. Neighborhoods

Consider a matrix $M$ of size $d$. We can view $M$ as a vector in $\mathbb{C}^{d^{2}}$ by writing its entries (from left to right, row to row) as the co-ordinates. From now on we consider $\mathcal{A}$ as a subset of $\mathbb{C}^{d^{2}}$. The matrix operations act as follows:
(i) addition: this will be viewed as vector addition;
(ii) multiplication: this is a bit more tricky. Take a matrix $M$ of size $d$ and a $d^{2}$-vector $M^{\prime}$. To obtain the vector $M^{\prime} M$, we first rewrite $M^{\prime}$ as a matrix, then do the matrix multiplication $M^{\prime} M$, and finally rewrite the result as a vector. This multiplying by $M$ is a linear operator on $\mathbb{C}^{d^{2}}$.
Next, we need a series of definitions. Note that here we are considering $M$ as a vector in $\mathbb{C}^{d^{2}}$. The norm $\|M\|$ indicates the length of this vector in $\mathbb{C}^{d^{2}}$. Then we have the following.
(i) Radius of $M$, that is, $r(M):=\min _{M^{\prime} \in \mathcal{A} \backslash\{M\}}\left\|M-M^{\prime}\right\|$.
(ii) Nearest neighbor of $M$, that is, $n(M)$ is an $M^{\prime}$ such that $\left\|M-M^{\prime}\right\|=r(M)$ (if there is more than one $M^{\prime}$ then choose one arbitrarily).
(iii) Ball of $M$, that is, $B(M)$ is the ball in $\mathbb{C}^{d^{2}}$ around $M$ with radius $r(M)$.

The following lemma will be used frequently in the proof. Let $x, y, z$ be three different points in $\mathbb{C}^{r}$. The angle $x y z$ is the angle between the rays $y x$ and $y z$. We understand that this angle is at most $\pi$. In $\mathbb{C}^{r}$ there are various ways of defining the angle between two vectors $x$ and $y$. (See [6] for a survey of some possible choices.) We are using the

$$
\angle(x, y)=\arccos \frac{\operatorname{Re}\left(y^{*} x\right)}{\|x\|\|y\|}
$$

notation, where $\operatorname{Re}\left(y^{*} x\right)$ is the real part of the Hermitian product, $\left(y^{*} x\right)=\sum_{i=1}^{r} \bar{y}_{i} x_{i}$. It is important to us that with this definition the law of cosines remains valid, and we have

$$
\begin{equation*}
\|x+y\|^{2}=\|x\|^{2}+\|y\|^{2}+2\|x\|\|y\| \cos (\angle(x, y)) . \tag{3.1}
\end{equation*}
$$

Lemma 3.1. For any positive integer $r$ and any constant $0<\alpha \leqslant \pi$, there is a constant $C(\alpha, r)$ such that the following holds. There are at most $C(\alpha, r)$ points on the unit sphere in $\mathbb{C}^{r}$ such that for any two points $z, z^{\prime}$, the angle zoz' is at least $\alpha$. (Here o denotes the origin.)

This lemma is equivalent to the statement that a unit sphere in $\mathbb{C}^{r}$ has at most $C(\delta, r)$ points such that any two has distance at least $\delta$. It can be proved using a simple volume argument. (See [5] for a more advanced approach.) The optimal estimate for $C(\alpha, r)$ is unknown for most pairs ( $\alpha, r$ ), but this value is not important in our argument.

Lemma 3.2. For any positive integer $r$ there is a positive constant $C_{1}(r)$ such that the following holds. Let $\mathcal{A}$ be a set of points in $\mathbb{C}^{r}$. Then for $z \in \mathbb{C}^{r}$ there are at most $C_{1}(r)$ elements $M$ of $\mathcal{A}$ such that $z \in B(M)$.

Proof. Let $M_{1}, \ldots, M_{k}$ be elements of $\mathcal{A}$ such that $z \in B\left(M_{i}\right)$ for all $i$. By the definition of $B(M)$ the distance between two distinct elements, $M_{i}$ and $M_{j}$, is at least as large as their distances from $z$. Then, by (3.1), the angle $M_{i} z M_{j}$ is at least $\pi / 3$ for any $i \neq j$. The claim follows from Lemma 3.1.

## 4. $K$-normal pairs

Let $K$ be a large constant to be determined. We call an ordered pair ( $M, M^{\prime}$ ) product $K$-normal if the ellipsoid $B(M) M^{\prime}$ contains at most $K(|\mathcal{A} \cdot \mathcal{A}| /|\mathcal{A}|)$ points from $\mathcal{A} \cdot \mathcal{A}$. (Recall that multiplying by $M^{\prime}$ is a linear operator on $\mathbb{C}^{d^{2}}$, and thus it maps a ball into an ellipsoid.)

Lemma 4.1. There is a constant $C_{2}=C_{2}(d)$ such that the following holds. For any fixed $M^{\prime}$ and $K \geqslant C_{2}$, the number of $M$ such that the pair ( $M, M^{\prime}$ ) is product $K$-normal is at least $\left(1-C_{2} / K\right)|\mathcal{A}|$.

Proof. Let $M_{1}, \ldots, M_{m}$ be the elements of $\mathcal{A}$, where $\left(M_{i}, M\right)$ is not product $K$-normal. By definition, we have

$$
\sum_{i=1}^{m}\left|B\left(M_{i}\right) M \cap \mathcal{A} \cdot \mathcal{A}\right| \geqslant \operatorname{Km} \frac{|\mathcal{A} \cdot \mathcal{A}|}{|\mathcal{A}|} .
$$

Set $\varepsilon:=m /|\mathcal{A}|$. By the pigeon hole principle, there is a point $z$ in $\mathcal{A} \cdot \mathcal{A}$ belonging to at least $K \varepsilon$ ellipsoids $B\left(M_{i}\right) M$. By applying the map $M^{-1}$, it follows that $z M^{-1}$ belongs to at least $K \varepsilon$ balls $B\left(M_{i}\right)$. By Lemma 3.2, $K \varepsilon=\mathrm{O}\left(d^{2}\right)=\mathrm{O}(d)$. Thus, $\varepsilon=\mathrm{O}(d) / K$, proving the claim.

By the same argument, we can prove the sum version of this lemma. An ordered pair ( $M, M^{\prime}$ ) is sum $K$-normal if the ball $B(M)+M^{\prime}$ contains at most $K(|\mathcal{A}+\mathcal{A}| /|\mathcal{A}|)$ points from $\mathcal{A}+\mathcal{A}$.

Lemma 4.2. For any fixed $M^{\prime}$, the number of $M$ such that the pair ( $M, M^{\prime}$ ) is sum $K$-normal is at least $\left(1-C_{2} / K\right)|\mathcal{A}|$.

## 5. Cones

For a ball $B$ in $\mathbb{C}^{r}$ and a point $x \notin B$, define the cone Cone $(x, B)$ as

$$
\text { Cone }(x, B):=\{t x+(1-t) B \mid 0 \leqslant t \leqslant 1\} .
$$

Now let $\alpha$ be a positive constant at most $\pi$. For two different points $x$ and $y$, we define the cone $\operatorname{Cone}_{\alpha}(x, y)$ as Cone $\left(x, B_{\alpha}(y)\right)$, where $B_{\alpha}(y)$ is the unique ball around $y$ such that the angle of Cone $\left(x, B_{\alpha}(y)\right)$ is exactly $\alpha$. (The angle of $\operatorname{Cone}\left(x, B_{\alpha}(y)\right)$ is given by $\max _{s, t \in B_{\alpha}(y)} \angle s x t$.)

Lemma 5.1. For any positive integer $r$ and any constant $0<\alpha \leqslant \pi$, there is a constant $C(\alpha, r)$ such that the following holds. Let $\mathcal{A}$ be a finite set of points in $\mathbb{C}^{r}$ and let $L$ be any positive integer. Then for any point $x \in \mathbb{C}^{r}$, there are at most $C(\alpha, r) L$ points $y$ in $\mathcal{A}$ such that the cone $\operatorname{Cone}_{\alpha}(x, y)$ contains at most $L$ points from $\mathcal{A}$.

Proof. Case 1: We first prove the case $L=1$. In this case, if $y \in \mathcal{A}$ and $\operatorname{Cone}_{\alpha}(x, y)$ contains at most one point from $\mathcal{A}$, then it contains exactly one point which is $y$. For any two points $y_{1}, y_{2} \in \mathcal{A}$ such that both $\operatorname{Cone}_{\alpha}\left(x, y_{1}\right)$ and $\operatorname{Cone}_{\alpha}\left(x, y_{2}\right)$ contain exactly one point from $\mathcal{A}$, the angle $y_{1} x y_{2}$ is at least $\alpha$, by the definition of the cones. Thus, the claim follows from Lemma 3.1.

Case 2: We reduce the case of general $L$ to the case $L=1$ by a random sparsifying argument. Let $\mathcal{Y}=\left\{y_{1}, \ldots, y_{m}\right\}$ be a set of points in $\mathcal{A}$ such that $\operatorname{Cone}_{\alpha}\left(x, y_{i}\right)$ contains at
most $L$ points from $\mathcal{A}$ for all $1 \leqslant i \leqslant m$. We create a random subset $\mathcal{A}^{\prime}$ of $\mathcal{A}$ by picking each point with probability $p$ (for some $0<p \leqslant 1$ to be determined), randomly and independently. We say that $y_{i}$ survives if it is chosen and no other points in $\mathcal{A} \cap \operatorname{Cone}_{\alpha}\left(x, y_{i}\right)$ are chosen. For each $y_{i} \in \mathcal{Y}$, the probability that it survives is at least $p(1-p)^{L-1}$. By linearity of expectations, the expected number of points that survive is at least $m p(1-p)^{L}$. Thus, there are sets $\mathcal{Y}^{\prime} \subset \mathcal{A}^{\prime} \subset \mathcal{A}$, where $\left|\mathcal{Y}^{\prime}\right| \geqslant m p(1-p)^{L}$ with the property that each point $y_{i} \in \mathcal{Y}^{\prime}$ is the only point in $\mathcal{A}^{\prime}$ that appears in $\operatorname{Cone}\left(x, y_{i}\right) \cap \mathcal{A}^{\prime}$. By the special case $L=1$, we conclude that $m p(1-p)^{L-1} \leqslant\left|\mathcal{Y}^{\prime}\right|=\mathrm{O}_{\alpha, r}(1)$. The claim of the lemma follows by setting $p=1 / L$.

## 6. Proof of the main theorem

Consider a point $M$ and its nearest neighbor $n(M)$. Let $M_{1}$ be another point, viewed as a matrix. We consider the multiplication with $M_{1}$. This maps the ball $B(M)$ to the ellipsoid $B(M) M_{1}$ and $n(M)$ to the point $n(M) M_{1}$.

Since the condition number $\kappa\left(M_{1}\right)$ is not too large, it follows that $B(M) M_{1}$ is not degenerate. In other words, the ratio between the maximum and minimum distance from $M M_{1}$ to a point on the boundary of $B(M) M_{1}$ is bounded from above by $\mathrm{O}_{\kappa}(1)$.

Let $b\left(M, M_{1}\right)$ be the largest ball contained in $B(M) M_{1}$ and Cone $\left(M, M_{1}\right)$ be the cone with its tip at $n(M) M_{1}$ defined by

$$
\operatorname{Cone}\left(M, M_{1}\right):=\left\{\operatorname{tn}(M) M_{1}+(1-t) b\left(M, M_{1}\right) \mid 0 \leqslant t \leqslant 1\right\}
$$

The assumption that $M_{1}$ is well conditioned implies that the angle of this cone is bounded from below by a positive constant $\alpha$ depending only on $\kappa$ and $d$. Thus, we can apply Lemma 5.1 to this system of cones.

Let $T$ be the number of ordered triples $\left(M_{0}, M_{1}, M_{2}\right)$ such that $\left(M_{0}, M_{1}\right)$ is product $K$-normal and $\left(M_{0}, M_{2}\right)$ is sum $K$-normal.

We choose $K$ sufficiently large so that the constant $\left(1-C_{2} / K\right)$ in Lemmas 4.1 and 4.2 is at least $\frac{9}{10}$. It follows that for any fixed $M_{1}$ and $M_{2}$, there are at least $\frac{4}{5}|\mathcal{A}|$ matrices $M_{0}$ such that $\left(M_{0}, M_{1}\right)$ is product $K$-normal and $\left(M_{0}, M_{2}\right)$ is sum $K$-normal. This implies that

$$
\begin{equation*}
T \geqslant \frac{4}{5}|\mathcal{A}|^{3} \tag{6.1}
\end{equation*}
$$

Now we bound $T$ from above. First we embed the triple $\left(M_{0}, M_{1}, M_{2}\right)$ into the quadruple $\left(M_{0}, n\left(M_{0}\right), M_{1}, M_{2}\right)$. Next, we bound the number of $\left(M_{0}, n\left(M_{0}\right), M_{1}, M_{2}\right)$ from above.

The $\kappa$-well-conditioned assumption of Theorem 2.2 guarantees that the quadruple ( $M_{0}, n\left(M_{0}\right), M_{1}, M_{2}$ ) is uniquely determined by the quadruple

$$
\left(M_{0} M_{1}, n\left(M_{0}\right) M_{1}, M_{0}+M_{2}, n\left(M_{0}\right)+M_{2}\right)
$$

In order to see this, set $A=M_{0} M_{1}, B=n\left(M_{0}\right) M_{1}, C=M_{0}+M_{2}$ and $D=n\left(M_{0}\right)+M_{2}$. Then $\left(M_{0}-n\left(M_{0}\right)\right) M_{1}=A-B$ and $M_{0}-n\left(M_{0}\right)=C-D$. Since $M-M^{\prime}$ is invertible for any $M \neq$ $M^{\prime} \in \mathcal{A}$, we have $M_{1}=(C-D)^{-1}(A-B)$. (This is the only place where we use this condition.) Since $M_{1}$ is also invertible (as it has a bounded condition number), it follows that $M_{0}=A M_{1}^{-1}$, $n\left(M_{0}\right)=B M_{1}^{-1}$ and $M_{2}=C-M_{0}$.

It suffices to bound the number of $\left(M_{0} M_{1}, n\left(M_{0}\right) M_{1}, M_{0}+M_{2}, n\left(M_{0}\right)+M_{2}\right)$.
We first choose $n\left(M_{0}\right) M_{1}$ from $\mathcal{A} \cdot \mathcal{A}$. There are, of course, $|\mathcal{A} \cdot \mathcal{A}|$ choices. After fixing this point, by Lemma 5.1 and the definition of product $K$-normality, we have $\mathrm{O}_{\kappa, d}(K(|\mathcal{A} \cdot \mathcal{A}| /|\mathcal{A}|))$ choices for $M_{0} M_{1}$. Similarly, we have $|\mathcal{A}+\mathcal{A}|$ choices for $n\left(M_{0}\right)+M_{2}$ and for each such choice, we have $O_{\kappa, d}(K(|\mathcal{A}+\mathcal{A}| /|\mathcal{A}|))$ choices for $M_{0}+M_{2}$. It follows that

$$
\begin{equation*}
T \leqslant|\mathcal{A} \cdot \mathcal{A}| \cdot \mathrm{O}_{\kappa, d}\left(K \frac{|\mathcal{A} \cdot \mathcal{A}|}{|\mathcal{A}|}\right) \cdot|\mathcal{A}+\mathcal{A}| \cdot \mathrm{O}_{\kappa, d}\left(K \frac{|\mathcal{A}+\mathcal{A}|}{|\mathcal{A}|}\right) \tag{6.2}
\end{equation*}
$$

Recall that $K$ is also a constant depending only on $\kappa$ and $d$. Putting (6.1) and (6.2) together, we obtain

$$
\frac{4}{5}|\mathcal{A}|^{3} \leqslant \mathrm{O}_{\kappa, d}\left(\frac{|\mathcal{A} \cdot \mathcal{A}||\mathcal{A}+\mathcal{A}|}{|\mathcal{A}|^{2}}\right),
$$

concluding the proof.
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J. Solymosi<br>Department of Mathematics University of British Columbia 1984 Mathematics Road<br>Vancouver, BC<br>Canada V6T 1Z2<br>solymosi@math.ubc.ca


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